

### www.avtronencoders.com

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# **ENCODER INSTRUCTIONS**

#### DESCRIPTION

The Avtron Model XR485 SMARTSafe<sup>™</sup> encoder is a severe duty incremental encoder for use in hazardous locations (also known as tachometer or rotary pulse generator). When coupled to a motor or machine, its output is directly proportional to shaft position (pulse count) or speed (pulse rate). The XR485 operates down to zero speed and can be used for both control and instrumentation applications.

#### CAUTION

The XR485 is designed for use in hazardous applications which require protection from gas or dust ignition for safe operation. Proper selection, wiring and installation procedures are essential to ensuring safe conditions.

Mechanically, the XR485 mounts on a NEMA 56C adapter flange or it can be foot mounted by using an optional foot mounting bracket kit. The XR485 utilizes magnetoresistive sensors. This proven technology is ideal for rugged environments since it is immune to contaminants that cause optical encoders to fail. These factors, make the XR485 ideal for demanding industries like paper, metals, and chemical processing.

The outputs are protected against short circuits and wiring errors. An Avtron XR485 SMARTSafe encoder is equipped with one or two XR5 sensor modules. Each module has a two-phase output (A, B) 90° out of phase, with complements ( $\overline{A}$ ,  $\overline{B}$ ), (A Quad B Output). A marker pulse with complement (Z,  $\overline{Z}$ ) is also present.

Output resolution on the XR485 is determined by the sensor only. Unlike older models, any PPRs can be mixed and matched. Selection of the rotor is based only on the shaft mounting requirements (and not PPR).

The XR5 removable sensor assembly has a diagnostic package that includes Adaptive Electronics and a Fault-Check output.

#### **ADAPTIVE ELECTRONICS**

A perfect duty cycle consists of a waveform whose "high" and "low" conditions are of the same duration (50%/50%). It is possible over time for the duty cycle and edge separation to change due to component drift, temperature changes, or mechanical wear. The Adaptive Electronics extend the life of the XR850 by constantly monitoring and correcting duty cycle and edge separation over time.



### INSTALLATION

#### WARNING

Installation should be performed only by qualified personnel. Safety precautions must be taken to ensure machinery cannot rotate and all sources of power are removed during installation.

Refer to the following attached installation drawings for installation information appropriate for specific hazardous locations: D53008: ATEX / IECEx Zone 1, 21 D52353: ATEX / IECEx Zone 2, 22 D52354: US and Canada Class I Division 1 Encoder D52355: US and Canada Class I Division 2

#### NOTE:

#### The equipment is intended for a fixed installation and should be mounted so as to avoid electrostatic charging. The XR850 is not considered as a safety device and is not suitable for connection into a safety system.

The XR485 construction materials contain less than 7.5% in total by mass of magnesium, titanium and zirconium. These materials are not considered as able to trigger an explosion in normal operating modes. These materials are not known to react with any explosive atmospheres to which the XR485 may be subject. It is however the responsibility of the end user to ensure that the XR485 is selected correctly for the potentially explosive atmosphere in which the equipment is to be put into service.

#### **Equipment needed for installation**

Supplied: XR485 Encoder Thread Locker (blue) Anti-seize (copper)

Not Supplied:

Socket Hd. Cap Screw 5/16" Hex Wrench (T-Handle style) 3/8-16 x 0.75 (4) Shaft Coupling Washer, Flat 5/16 (4) Motor Adapter Flange Washer, Lock 5/16 (4) Dial Indicator Model XRB3 Isolator for Division 1, Zone 0, 1, 20 and 21 applications (Sold Separately)

#### **DRIVE INSTALLATION INSTRUCTIONS**

The encoder must be driven by a positive drive rather than a friction drive. The following means of coupling are acceptable when properly installed: Direct Coupling, Timing Belt/Pulleys, Chain/Sprockets. With a direct drive, use a flexible disc coupling and align the shafts as accurately as possible. EXAMPLE: For a size 62 Thomas Miniature Coupling angular misalignment must be less than 1.34°, parallel misalignment less than 0.028", and axial float less than  $\pm 0.031$ ". The encoder should not be subjected to any axial thrust. Overhung loads should also be minimized. Installations using timing belts/pulleys should have just enough belt tension to eliminate belt sag. Excessive tension will shorten belt and bearing service life. If a rubber slinger disc is used, position it on the shaft so it will rotate freely.

#### CAUTION

Do not force or drive the coupling onto the shaft, or damage to the bearings may result. The coupling should slide easily on the shaft. Remove nicks and burrs if necessary. Consider driving shaft endplay when positioning coupling.

For more details on alignment specifications, measurement techniques, and special considerations in specifying and installing drive components, refer to separate installation instructions in the

#### **Avtron PULSE GENERATOR HANDBOOK. NEMA 56C FACE MOUNTING INSTRUCTIONS**

- Apply anti-seize compound [copper], included, to inner 1) circumference of coupling (both motor and encoder side).
- 2) Loosen set screws in coupling and apply thread locker to set screws.
- 3) Place coupling on motor shaft, inserting to depth per manufacturer's instructions.
- 4) Attach coupling to motor shaft using set screws per manufacturer's instructions.
- 5) Bolt mounting flange (flowerpot) to motor C-Face, using thread locker with fasteners, included.
- Slide encoder shaft into other side of coupling. DO NOT 6) FORCE. Ensure 1/4" keyway aligns with coupling set screw location.
- Ensure C-Face on mounting flange matches and aligns with 7) encoder C-Face precisely.
- Apply thread locker to hex cap screws. 8)
- 9) Align bolt holes of encoder and flange, thread in (4) hex cap screws, using lock washers.
- 10) Tighten set screws on encoder side of coupling.

#### FOOT MOUNTING INSTRUCTIONS

Equipment needed for installation Supplied:

- 1 Foot Bracket (A36261/A25448) 4.
- Nut, Hex 5/16-18 (4) 2. Soc. Hd. Cap Screw 5.
  - 3/8-16 x .75 (4)
- Washer, Flat 5/16 (4) 6.
- Washer, Lock 5/16 (4) 7. Thread Locker (blue)
- 3. Hex Hd. Cap Screw 5/16-18 x 1.50 (4)

Not Supplied:

1/2" Wrench 5/16" Hex Wrench (T-Handle style) **Dial Indicator** 

The NEMA 56C face is the preferred mounting method for the XR485. In certain cases, however, it may be necessary to foot-mount this unit. The optional foot mounting bracket kit, Option 1, will be required for standard installations or replacement of Northstar RIM6200 units. To replace BC42 or BC46 units, use Option 2 foot mount kit. Read all of the following instructions and the Avtron PULSE GENERATOR HANDBOOK prior to beginning any work.

The XR485 performance and life will be directly affected by the installation. Following this sequence of steps is recommended.

- Clean and inspect motor/driver shaft. Do not use force to 1) assemble coupling onto motor/driver shaft. The foot mounting bracket must be secured to a flat, rigid, vibration free steel or aluminum base which can be machined to accept 5/16-18 mounting hardware.
- Temporarily mount the XR485 to the foot bracket, install the 2) coupling to the XR485 and driver, and verify that the location is suitable for installation.
- If the XR485 encoder, bracket and coupling are suited to the 3) area, check motor/encoder shaft alignment with a straight edge from multiple positions around the shaft circumference to verify that it meets specifications.
- While maintaining alignment, precisely mark the position of the 4) foot bracket on its mounting base.
- Remove the XR485. Transfer punch or layout the mounting hole 5) pattern as indicated on outline drawing.
- Machine four, 3/8" dia through holes or tap four, 5/16-18 holes 6) in center of base slots to give some degree of freedom in final alignment.
- Reinstall the XR485 with the flexible coupling loosely in place, 7) and tighten down all mounting hardware. Check motor/encoder shaft alignment with a straight edge from multiple positions around the shaft circumference to verify that it meets specifications. Use thread locker supplied on cap screws which mount XR485 to foot bracket.
- Ensure any flat or keyway on the motor and encoder shaft are 8) aligned with the set screw holes of the flexible coupling. Apply thread locker to coupling set screws and tighten per manufacturer's recommendations.
- 9) Recheck alignment and tighten all hardware after first several hours of operation.

MINIMIZE DOWN-TIME: Should XR485 replacement be required, leave the foot mounting bracket installed on its base and mount the new XR485 to the bracket. This maintains the original alignment.

#### WIRING INSTRUCTIONS

Refer to the isntallation drawings referenced above for wiring diagrams. Use the drawing appropriate for the encoder's installation location. Information on specific connector pinouts and phasing can be found on labels on the encoders and in tables included in these instructions.

#### CAUTION

SMARTSafe encoders include a local ground lug for customer convenience and encoder frame grounding if required to meet local electric code requirements or site operator protection standards. This is NOT the required intrinsic safety ground connection required for hazard protection against ignition of explosive atmospheres.

The XR485 can be wired for single phase or two phase, either with or without complements, with or without markers. For bidirectional operation, in most cases Phase A channel typically leads phase B channel for clockwise shaft rotation as viewed from the anti-drive or accessory end of the motor. See pinout and phasing tables for exceptions.

#### NOTE:

#### Wiring option "G" provides a pinout compatible with Northstar<sup>™</sup> encoders, with a cable shield connection on pin 10. Note that this option does not ground the shield.

#### **CORRECTIVE ACTION FOR PHASE REVERSAL**

- Remove Power. 1)
- Exchange wires on cable, either at encoder cable end, or at 2) speed controller end (but not both).
  - Single Ended 2 Phase Wiring (see wiring diagram) a) Exchange A and B at the use end of the wires.
  - Differential 2 Phase Wiring (see wiring diagram) b)

Exchange either A with A- in the phase A pair OR B with B- in the phase B pair but NOT both.

- 3) Apply Power.
- Verify encoder feedback is correct, using hand rotation of shaft, or jog mode of the speed controller.

Interconnection cables specified in the wire selection chart are based on typical applications. Cable must be selected and installed in accordance with regional standards. Typical interconnection cable is 4 twisted pair + overall shield. Recommended cable is Avtron B37178. Alternates are Belden P/N 1064A or Rockbestos 04P-18 I/S-OS. Actual cables should be picked based on specific application requirements such as abrasion, temperature, tensile strength, solvents, etc. General electrical requirements are: stranded copper, 20 through 16 AWG, twisted wire pairs, braid or foil individual shields or over-all shield with drain wire, .03uF of maximum total mutual or direct capacitance and outer sheath insulator. 20 AWG wire should not be used for DC power to the encoder for runs greater than 200 feet and 22AWG should not be used for runs greater than 100 ft. This is to minimize voltage drop between the encoder and the XRB3 isolator. The smaller conductors are acceptable for the signal lines.

#### NOTE

When using the industrial connector ("G" and "P" options), the minimum wire size is 20 gauge, and 20 gauge (only) wire ends must be tinned with solder before connection at the screw terminals.

#### MAINTENANCE

#### **GENERAL**

This section describes routine maintenance for the Avtron XR485 Encoder. For support, contact Avtron's field service department at 216-642-1230. For emergency after hours service contact us at 216-641-8317.

The XR485 SMARTSafe encoder circuitry includes a diagnostic package that includes Adaptive Electronics and a Fault-Check output.

#### **FAULT-CHECK**

After power-up and the internal rotor position is checked by the sensor, the Fault-Check LED will turn green.

If the adaptive electronics reach their adjustment limit for any reason, the Fault-Check alarm and LED will notify the drive and operator of an impending failure. The LED will turn red if the Adaptive Electronics reach their adjustment limit. This output occurs before an actual failure, allowing steps to be taken to replace the unit before it causes unscheduled downtime. Fault-Check annunciation is available as an "alarm" output through the connector (zone 2 cofiguration only) and as an integral LED.

#### **TROUBLESHOOTING:**

If the drive indicates a loss of encoder/tach fault and the XR485 faultcheck LED is not illuminated, check the encoder power supply. If power is present, check polarity: one indicator of reversed power supply is that all outputs will be high at the same time. If the drive indicates encoder fault, but the LED shows GREEN, then check the wiring between the drive and the encoder. If the wiring appears correct and in good shape, test the wiring by replacing the XR5 sensor module. If the new module shows GREEN, and the drive still shows encoder loss/tach fault, then the wiring is faulty and should be repaired or replaced.

If the alarm output and/or LED indicate a fault (RED):

- 1. Remove an end sensor plate or the second sensor, and use the built-in gauge to check the location of the rotor (see Figure 1).
- 2. Remove the XR5 sensor from the housing. Clean the housing mounting surface for the XR5 sensor and the XR485 housing.

If the alarm output and/or LED indicate a fault (RED) on a properly mounted XR5 sensor and the rotor is properly located, replace the XR5 sensor.

An oscilloscope can also be used to verify proper output of the XR5 encoder at the encoder connector itself and at the drive/controller cabinet. If the outputs show large variations in the signals at steady speed (jitter or "accordion effect", See Figure Below), check rotor position. If the rotor position is correct, the motor or shaft may be highly magnetized. Replace any magnetized shafts with non-magnetic material (stainless/aluminum). Consider replacing the sensors with super-shielded models, option -004.



XR485	R485 PART NUMBERS AND AVAILABLE OPTIONS INCLUDING AV5 SENSORS														
Model	Temp Bating	Foot	Style	Lef	t Module		Right Module			Connector	Modifi-				
Model		Bracket	Otyle	Line Driver	PPR	1	Line Driver	Р	PR	Options	cations				
XR485	N20°C to 80°C C40°C to 80°C	X- none 1- A36261 STD 2- BC42/46 style (A25448)	S- single shaft D- dual shaft	See Line Driver Connection Option Chart	X- none         6-           F- 60         3-           G- 100         4-           H- 120         5-           A- 128         D           L- 240         8-           N- 256         9-           P- 300         0-           E- 360         8-           B- 480         Q-           Q- 500         R-           S- 600         V-           V- 900         J-           J- 960         Y-           Y- 1024         Z-           Z- 1200         X-	- 1800 - 2000 - 2048 - 2500 - 4096 - 4800 - 5000 -special	See Line Driver Connection Option Chart	X- none F- 60 G- 100 H- 120 A- 128 L- 240 N- 256 P- 300 E- 360 B- 480 Q- 500 R- 512 S- 600 V- 900 J- 960 Y- 1024	Z- 1200 6- 1800 3- 2000 4- 2048 5- 2500 D- 4096 8- 4800 9- 5000 0-special	See Line Driver Connection Option Chart	000- none 400*- Select alternate PPR assignment code 005- Krytox bearings 018- ADD iso- lator 900- Special cable length 004- Super magnetic shielding				

XR5 Sens	or Part Numbers					
Model	Line Driver	PPR	Connector Options	Modifications		
XR5-	See Line Driver Connection Option Chart	X- none         S- 600           F- 60         V- 900           G- 100         J- 960           H- 120         Y- 1024           A- 128         Z- 1200           L- 240         3- 2000           N- 256         4- 2048           P- 300         5- 2500           E- 360         D- 4096           B- 480         8- 4800           Q- 500         9- 5000           R- 512         0-special	See Line Driver Connection Option Chart	<ul> <li>000- none</li> <li>004- Super Magnetic Shielding</li> <li>005- Special 97mm Rotor (see special manual)</li> <li>4xx- Special PPR (see table)</li> <li>9xx- Special Cable Length (xx=ff/0.3m)</li> </ul>		

Special PPR Option Code	PPR
401	1270
402	150
403	50
404	512
405	N/A
406	6000

			Line Driver Options								
		Description	ATEX / IECEx Zone 1 & 21	ATEX / IECEx Zone 2 & 22	Class I Div. 1 & Zone 0	Class I Div. 2 Listed	Class I Div. 2 Recognized				
		Voltage In / Out	5-7 / 5	5-24 / 5-24	5-7 / 5	5-24 / 5-24	5-24 / 5-24				
		Line Driver Code	Н	7	F	G	R				
	Code	Required Isolator	XRB3	None	XRB3	None	None				
	А	10 Pin MS W/O Plug	$\checkmark$	$\checkmark$	$\checkmark$		$\checkmark$				
	В	10 Pin MS With Plug	$\checkmark$	✓	$\checkmark$		$\checkmark$				
	E	7 Pin MS W/Plug A-quad-B Std. Phasing	$\checkmark$	$\checkmark$	$\checkmark$		$\checkmark$				
S	F	7 Pin MS W/Plug A, A\ Std. Phasing	$\checkmark$	✓	$\checkmark$		✓				
on	J	7 Pin MS W/Plug A, B, Z Std. Phasing	$\checkmark$	✓	$\checkmark$		$\checkmark$				
pti	к	7 Pin MS W/Plug A, A B,B\ Std. Phasing	$\checkmark$	✓	$\checkmark$		$\checkmark$				
r O	S	7 Pin MS W/Plug A-quad-B Dyn. Phasing	$\checkmark$	✓	$\checkmark$		$\checkmark$				
to	т	7 Pin MS W/Plug A, A\ Dyn. Phasing	$\checkmark$	~	$\checkmark$		$\checkmark$				
nec	U	7 Pin MS W/Plug A, B, Z Dyn. Phasing	$\checkmark$	~	$\checkmark$		$\checkmark$				
on	۷	7 Pin MS W/Plug A, A B,B\ Dyn. Phasing	$\checkmark$	~	$\checkmark$		✓				
U U U	Р	Large Industrial Style Std. Pinout & Plug	$\checkmark$	✓	$\checkmark$						
acl	G	Large Industrial Style Northstar Pinout & Plug	$\checkmark$	✓	$\checkmark$						
<b>ART</b>	R	10 Pin mini Twist Lock with Plug	$\checkmark$	✓	$\checkmark$						
MA	W	Flexible Cable with Sealing Gland	$\checkmark$	$\checkmark$	$\checkmark$						
S	4	Conduit Box, Terminal Block & 1/2" NPT	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$					
	5	Conduit Box, Terminal Block, 3/4" NPT+Cord	✓	~	~	~					
	6	Conduit Box, Terminal Block & 1" NPT	~	~	~	~					
	7	Conduit Box, Terminal Block & 25mm	~	~	~	~					

# **SPECIFICATIONS**

#### ELECTRICAL

A. Operating Power (Vin)	
1. Volts	.See Line Driver Option Chart
2. Current	. Each output, 100mA Nom. 355mA Max.
B. Output Format	
1. 2Ø & Comp	. A, A, B, B (differential line driver)
2. Marker	1/Rev, Z, Z
C. Signal Type	.Incremental, Square Wave, 50 ±10% Duty Cycle.
D. Direction Sensing	.Ø A leads Ø B for CW rotation as viewed from
	the back of the tach looking at the non-drive end
	of the motor.
E. Transition Sep	.15% minimum
F. Frequency Range	.0 to 165,000 Hz
G. PPR	.8-5000
H. Line Driver Specs	.See table
I. Connectors	.See connector options on page 1
J. Integral LED Indicator	.GREEN: power on, unit ok. RED: alarm on

#### MECHANICAL

A. Shaft Inertia	.21 Oz. In. Sec. <sup>2</sup>
B. Acceleration	.5000 RPM/Sec. Max.
C. Speed	.5400 RPM Max.
D. Weight	.14-16 lbs. [ 6-7.5 kg.]
E. Radial Load	.350 Lbs [1500N] at 1E08 revolutions
	(900 hrs at 1800 RPM) 35 lbs [150N] at 5E09
	resolutions (5000 hrs at 1800 RPM)
F. Axial Load	.115 lbs [510N] at 1E08 resolutions
	12 lbs [51N] at 5E09 resolutions

#### ENVIRONMENTAL

Solid cast aluminum stator and rotor

7.5% of magnesium, titanium and zirconium total by mass Fully potted electronics, protected against

oil and water spray Operating temp see rating on P/N chart See "Description" section for information on hazardous location environments

XR485 Connector Spare Parts									
Style	Code	En	coder Side	Customer Side					
Large		314879	Base	314880	Hood				
Industrial	P, G	314878	Terminals	314877	Terminals				
"Epic"									
		Box	Recepticle	ninals 314877 Terminals cle Plug ndard 315932 Standard river "R" 316445 Line Driver "R" 411216 Bushing 411217 Bushing 411218 Bushing 411219 Bushing cle Plug ndard 315932 Standard river "R" 316446 Line Driver "R"					
		315933	Standard	315932	Standard				
		431079	Line Driver "R"	316445	Line Driver "R"				
10 pin MS	А, В			411216	Bushing				
				411217	Bushing				
				411218	Bushing				
				411219	Bushing				
		Box	Recepticle		Plug				
		316297	Standard	315932	Standard				
7 Pin MS	E, F, J, K, S. T. U. V	431080	Line Driver "R"	316446	Line Driver "R"				
	-, , -, .			411218	Bushing				
				411219	Bushing				
Conduit Box	4,5,6,7			364987	Terminal Plug				
10 pin mini MS	R	431081	Base	316447	Ρίμα				
Twist Lock		471748	Gasket	510+1/	1.05				

				Line Driver Specifications Isolator Specifi						
		Code	н	7	F	G	XRB3			
	Description	Symbol	ATEX / IECEx Zone 1 & 21(ia)	ATEX / IECEx Zone 2 & 22	Class I Div. 1 & Zone 0	Class I Div. 2 Listed	ATEX/IECEx Zone 1&21(ia) + Class I Div 1&Zone 0	Units		
	Line Driver		7272	7272	7272	7272	IXDF604			
Input '	Voltage (Nominal)	V <sub>IN</sub> / V <sub>S</sub>	5-7	5-24	5-7	5-24	12-24	V <sub>DC</sub>		
Input \	/oltage (Max Safe)	UM	N/A	N/A	N/A	N/A	30	v		
Input	Current (no load)	I <sub>IN</sub> / Is	80	80	80	80	150	mA		
Input	Current (Typical)	I <sub>IN</sub> / Is	100	200	100	200	450	mA		
Inpu	t Current (Max.)	l <sub>in</sub> / ls	140	300	140	300	900	mA		
Output	: Voltage (nominal)	V <sub>H</sub>	N/A	N/A	N/A	N/A	6.8	V <sub>DC</sub>		
Output Vo	oltage Min.(@140mA)	V <sub>H</sub>	N/A	N/A	N/A	N/A	5	V <sub>DC</sub>		
Output V	oltabe Max(No Load)	V <sub>H</sub>	N/A	N/A	N/A	N/A	7.14	V <sub>DC</sub>		
Outpu	t Current (@6.8V)	I <sub>H</sub>	N/A	N/A	N/A	N/A	115	mA		
Outp	ut Current (@5V)	I <sub>H</sub>	N/A	N/A	N/A	N/A	140	mA		
Output C	urrent (short circuit)	Iн	N/A	N/A	N/A	N/A	420	mA		
Voltage O	utput High (Nominal)	V <sub>OH</sub>	5	V <sub>IN</sub> -1	5	V <sub>IN</sub> -1	Vs-1	V <sub>DC</sub>		
Voltage C	utput Low (Nominal)	Vol	.5	.5	.5	.5	.4	V <sub>DC</sub>		
Signal C	urrent (Continuous)	I <sub>OH</sub> / I <sub>OL</sub>	100	100	100	100	2580	mA		
Signa	al Current (Peak)	I <sub>OH</sub> / I <sub>OL</sub>	1500	1500	1500	1500	3000	mA		
Outp	out Resistance Ω	R <sub>OH</sub> / R <sub>OL</sub>	15	15	15	15	7	Ω		
	Cable Drive		500	5-15Vin=500 24Vin = 250	500	5-15Vin=500 24Vin = 250	1000	ft.		
	Reverse Voltage		Yes	Yes	Yes	Yes	Yes			
Protection	Short Circuit		Best	Good	Best	Good	Best	ĺ		
	Transient		Good	Good	Good	Good	Best			
	+Vout		no	Yes	no	Yes	no			
	Alarm		no	Yes	no	Yes	no			
A la 1999	LED		Yes	Yes	Yes	Yes	Yes			
Aidfill	+Vout		Reverence Signal fo	r Alarm Circuit, Outp	ut Voltage = Input Vol	tage	*			
	Alarm		Open Collector, nor	mally off, goes low o	n alarm, sink 100mA r	nax, See Connecto	r Pinouts for Availability			
	LED		Green = Power On,	Red = Alarm						

# THIN-LINE Ⅱ<sup>™</sup> Application Examples

Applies to all XR685 Zone 2 & Division 2models with wiring options "W", "P", "4", "5", "6", "7", "A" and "B". Remote alarm not available for Zone 0, Zone 1 or Division 1.

#### ALARM OUTPUT CONNECTION

Avtron encoders provide an alarm signal if maintenance is required under specific circumstances. An alarm LED indicator is also available. Green indicates power on, red indicates alarm on. Following are application examples provided to help install the alarm output.

Example 1. Alarm output using +V(OUT). +V(OUT) is equal to +V, the encoder power supply.



Example 2. Alarm Output Using Separate \* VDC Power Supply and Relay.



See the following Installation Drawings for Wiring Information

D53008: ATEX / IECEx Zone 1 & 21

D52353: ATEX / IECEx Zone 2 & 22

D52354: Division 1

D52355: Division 2

NOTE: Remote alarm is not functional for Division 1, Zone 0 or Zone 1

# **PINOUTS AND PHASING**

Phasing is defined as the direction of rotation for which phase A leads B as viewed from the back of the Encoder

viewed from the back of the Encoder	Option Code	Phasing	Signal	0V Gnd	A+	B+	Z+	* Alm+	+Vin		 B-		* Alm
10 Pin MS AvtronPinout	A,B	CW	Pin #	Α	D	Е	С	F	В	G	Н	I	J
10 Pin, Industrial, Avtron Pinout	Р	CW	Pin #	1	2	3	4	5	6	7	8	9	10
10 Pin, Industrial, Northstar Pinout	G	CW	Pin #	1	2	3	4	NC	6	7	8	9	NC
10 Pin MS Mini Twist Lock	R	CW	Pin #	F	Α	В	С	NC	D	Н	J	K	NC
Conduit Box W/10 Pin Terminal Block	4,5,6,7	CW	Pin #	1	2	3	4	5	6	7	8	9	10
10 Wire Cable	W	CW	Color	BLK	GRN	BLU	ORG	BRN	RED	YEL	GRA	WHT	VIO

Phasing is defined as the direction of rotation for which phase A leads B as

rotation for which phase A leads B as	Option	Phasing	Signal	00							
viewed from the back of the Encoder	Ċode	Thasing	Jighat	Gnd	A+	B+	Z+	+Vin	A-	B-	Z-
7 Pin MS, Avtron / BEI Pinout (A,AB,B\)	K	CW	Pin #	F	Α	В	NC	D	С	Е	NC
7 Pin MS, Avtron / BEI Pinout (A,A\)	F	CW	Pin #	F	Α	NC	NC	D	С	NC	NC
7 Pin MS, Avtron / BEI Pinout (A,B,Z)	J	CW	Pin #	F	Α	В	С	D	NC	NC	NC
7 Pin MS, Avtron / BEI Pinout (A,B)	E	CW	Pin #	F	А	В	NC	D	NC	NC	NC
7 Pin MS, Dynapar Pinout (A,AB,B\)	V	CCW	Pin #	F	А	В	NC	D	С	Е	NC
7 Pin MS, Dynapar HS35 Pinout (A,A\)	Т	CCW	Pin #	F	А	NC	NC	D	С	NC	NC
7 Pin MS, Dynapar HS35 Pinout (A,B,Z)	U	CCW	Pin #	F	А	В	С	D	NC	NC	NC
7 Pin MS, Dynapar HS35 Pinout (A,B)	S	CCW	Pin #	F	A	В	NC	D	NC	NC	NC

\* Remote alarm function not available with line driver options "H", "7" or "F" (Zone 0, Zone 1 or Class I Div I)

## **OUTLINE DRAWING**



Nidec Industrial Solutions | 243 Tuxedo Avenue | Cleveland, Ohio 44131 | encoderhelpdesk@nidec-industrial.com +1 216-642-1230 | www.avtronencoders.com

XR485 SMARTSafe<sup>™</sup>



A **Nider** BRAND

XR485 SMARTSafe<sup>™</sup>

Rev: 10-06-2020 10

MT9162TAAM2 284AX

Rev: 10-06-2020

11

EA0878 A ADD SPECIAL CONDITIONS FOR SAFE USE PATTON 6/24/15 SHADDUCK

SNOISIA38

DESCRIPTION

ECN NO BEA

APPROVED

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NULESS OTHERWISE SPECIFIED THE ABOVE NOTES APPLY

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Coution: Be sure to remove power before wring the encoder. Ground the cable shield. Ground Lug for customer convenience and encoder frame grounding with the wor wrre if regi interconnection cables specified are based on typical applications. Cable wust be selected canadian electrical code. Physical properties of cable such as arradium. Temperature, tens ceneral electrical code. Physical properties of cable such as arradian. Temperature, tens ceneral electrical code. Physical properties of cable such as arradian. Temperature, tens ceneral electrical requirements are: Stranded copper, 20 through 16 and (industrial epic of escience of the undiversion). Temperature epic of the individual such service and the area of the area of the area of the area contension. Temperature epic of the constance of the area of the area of the area escience of the area of the second and the area of the a

EUCODER: 1. WHEN THE ENCODER IS MARKED AS "ic" THE POWER SUPPLY SITUATED IN THE SAFE AREA A BE SELECTED AND INSTALLED IN ACCORDANCE WITH IEC/EN 60079-74 AND IEC/EN 60079-73 2. THE EQUIPMENT SHOULD BE MOUNTED SO AS TO AVOID ELECTROSTATIC CHARGING. AMAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8901 EAST PLEASANT MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8901 EAST PLEASANT MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8901 EAST PLEASANT MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8901 EAST PLEASANT MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8901 EAST PLEASANT MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8901 EAST PLEASANT MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8001 EAST PLEASANT MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8001 EAST PLEASANT MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8001 EAST PLEASANT MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8001 EAST PLEASANT MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8001 EAST PLEASANT MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8001 EAST PLEASANT MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8001 EAST PLEASANT MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8001 EAST PLEASANT MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8001 EAST PLEASANT MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8001 EAST PLEASANT MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8001 EAST PLEASANT MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION AUTOMATION AUTO

SPECIAL CONDITIONS FOR SAFE USE:

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THE XR --- FAMILY OF ENCODERS IS CERTIFIED FOR USE GROUP IIC WHEN MARKED CE GROUP II, CATEGORY 3 (ZONE 2) GAS GROUP IIC WHEN MARKED CE USED WITH A SELV OR EQUIVILENT POWER SUPPLY THAT LIMITS VOLTAGE ANI GROUP II, CATEGORY 3 (ZONE 22) DUST GROUP IIIC WHEN MARKED C

ECEXILECATES OF CONFORMITY TRAC12ATEX0003X, IECEX TRC12.0009X BSEN61000-6-4:2007 AND BSEN61000-6-2:2005 IEC60079-11:2011, EN60079-11:2012

THE XR --- FAMILY OF ENCODERS HAS BEEN EVALUATED TO BE COMPLIANT WITH: IEC60079-0:2011, EN60079-0:2012/A11:2013 IEC60079-11:2011 EN60079-11:2013

CONNECTOR OPTION CODE = 7 FOR ZONE 2 & 22 CONNECTOR OPTION CODES = A, B, C, D, E, F, C, H, J, K, L ALL OTHER CODE LOCATIONS ARE NOT RELEVANT TO INTRINS SEE INSTRUCTION SHEETS FOR DEFINITIONS SEE INSTRUCTION SHEETS FOR DEFINITIONS

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RECOGNIZED MODELS ARE INTENDED TO BE FACTORY WIRED IN ACCORDANCE WITH IS 12.12.01 CLAUSE 8.8.1.

THIS EQUIPMENT HAS BEEN EVALUATED FOR USE IN A MAXIMUM AMBIENT TEMPERATURE OF 80°C. CONSIDERATION MUST BE GIVEN TO ENSURE FIELD WIRING IS SUITABLY RATED.

Cet équipement a été évalué pour une utilisation dans une température ambiante maximum de 80 °.C. Il faut tenir compte pour assurer le câblage est convenablement clasé.

REFER TO THE WIRING DIAGRAMS ON THE ENCODER AND IN SPECIFIC MODEL INSTRUCTION SHEETS FOR SPECIFIC CONNECTOR PIN OUTS AND PHASING TABLES FOR EACH CONNECTOR STYLE OPTION.