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ENCODER INSTRUCTIONS

DESCRIPTION

The Avtron XR56, SMARTSafeTM is a modular, two piece incremental encoder for hazardous atmosphere applications. It provides a two phase, A Quad B frequency (pulse) output, with complements. The XR56 mounts on a 4.5" (NEMA 56C) Face.

CAUTION

The XR56 is designed for use in hazardous applications which require protection from gas or dust ignition for safe operation. Proper selection, wiring and installation procedures are essential to ensuring safe conditions.

Because the XR56 is modular, there are no bearings or couplings required. This, combined with the latest magnetoresistive (MR) sensor technology, allows the XR56 to provide superior mechanical performance and increased reliability.

An Avtron XR56 can be configured with one or two independent outputs. Each output has six signals: (A, B) 90° out of phase, with complements (\overline{A} , \overline{B}). A marker pulse with complement (Z, \overline{Z}) is also provided.

Output resolution on the XR56 is determined by the sensor only. Unlike older models, any PPRs can be mixed and matched. Selection of the rotor is based only on the shaft mounting requirements (and not PPR).

ADAPTIVE ELECTRONICS

A perfect duty cycle consists of a waveform whose "high" and "low" conditions are of the same duration (50%/50%). It is possible over time for the duty cycle and edge separation to change due to component drift, temperature changes, or mechanical wear. The Adaptive Electronics extend the life of the XR56 by constantly monitoring and correcting duty cycle and edge separation over time.



XR56 SMARTSafe[™]

4 1/2" C-FACE MOUNT MODULAR FOR HAZARDOUS APPLICATIONS

INSTALLATION

WARNING

Installation should be performed only by qualified personnel. Safety precautions must be taken to ensure machinery cannot rotate and all sources of power are removed during installation.

Refer to the following attached installation drawings for installation information appropriate for specific hazardous locations: D53008: ATEX / IECEx Zone 1, 21 D52353: ATEX / IECEx Zone 2, 22 D52354: US and Canada Class I Division 1 Encoder D52355: US and Canada Class I Division 2

NOTE

The equipment is intended for a fixed installation and should be mounted so as to avoid electrostatic charging. The XR56 is not considered as a safety device and is not suitable for connection into a safety system.

The XR56 construction materials contain no more than 7.5% in total by mass of magnesium, titanium and zirconium. These materials are not considered as able to trigger an explosion in normal operating modes. These materials are not known to react with any explosive atmospheres to which the XR56 may be subject. The construction materials do include aluminum. As such care should be taken to avoid the possibility of ignition from impact or friction. It is the responsibility of the end user to ensure that the XR56 is selected correctly for the potentially explosive atmosphere in which the equipment is to be put into service.

The XR56 installation is similar to AV56. Installation and removal videos for the AV56/67/85/115 are available on Avtron's web site. Refer to the back page of these instructions for outline and mounting dimensions. The motor must comply with 1998 NEMA MG 1, section 4, for tolerances on diameters and runout for shafts and accessory faces. Axial float or endplay plus rotor location tolerance must be less than ± 0.050 ".

EQUIPMENT NEEDED FOR INSTALLATION								
Provided	Optional	Not Provided						
 AV56 Stator/Housing Socket Hd Cap Screw 3/8"-16 x 1.25" (qty 4) AV56 Rotor Socket Set Screw #M4 x 8mm (qty 2) or Pre-Installed Cam Screw Thread locker (Blue) 	 Extended Shaft Cover w/ Screws 6-32 x 0.31" (qty 4) Lock Washers Thru Shaft Cover w/ V-Ring Seal and Silicone Lubricant XRB3 Isolator Model XRB3 for Division I, Zone 0, 1, 20 and 21 Applications (Sold Separately) 	 Phillips Screwdriver 2mm Hex Wrench (T-Handle Style for set screw Rotors) 3mm Hex Wrench 5/16" Hex Wrench 						

In preparation for installing the Model XR56 encoder, it is first necessary to clean both the accessory motor shaft and the mounting face. These surfaces must be inspected and any paint, burrs, or other surface imperfections removed.

Installation procedures should be performed only by qualified personnel. Safety precautions must be taken to ensure machinery cannot rotate and all sources of power are removed during installation.

ROTOR INSTALLATION

The motor shaft must project at least 0.66" from the motor face. For set screw rotors only: Apply anti-seize compound to the motor shaft. For all rotors: Slide the rotor onto the shaft with the marking "Motor side" facing in, (toward the motor face). The rotor centerline must match the sensor centerline. To accomplish this, use the rotor locating gauge (A28503) and slide the rotor onto the shaft until it is in the proper position as shown in Figure 1. If a gauge is not available, use the stator housing alignment grooves as shown in Figure 3.

STANDARD CAM SCREW ROTOR INSTALLATION

Turn the cam screws of the rotor in the directions shown on the rotor to engage the cams. Tighten to 50-60 in-lb [5.6 - 6.8 N-m] (Fig 2) using the 3mm hex wrench. Total cam screw rotation will be less than one turn.

CAUTION

Do not adjust the cam screws before motor shaft mounting; bottoming out the screws, or backing them out excessively, can lead to insufficient shaft holding force. Thread locker is pre-applied on the cam screws.

LARGE BORE SET SCREW ROTOR INSTALLATION

Apply thread locker to the rotor set screw holes, preferably from the inside of the rotor bore before mounting. Tighten the rotor set screws to 15 in-lb [2 N-m] using the 2mm T-handle hex wrench.

CAUTION

Use only a T-handle or torque hex wrench to tighten set screws; using a right angle wrench will not provide enough holding force, and the rotor may slip.

STATOR HOUSING INSTALLATION

The stator housing is attached to the motor using four socket head cap screws (4) 3/8"-16 x 1.25", locating on a 5.88" bolt circle. Longer bolts (not included), are required for sandwich installation between a motor and a brake. Install the four mounting bolts using thread locker and torque to approximately 20-30 ft lbs [27 to 40 N-m] using the 5/16" T-handle hex wrench.

VERIFY ROTOR LOCATION

To ensure the rotor is properly located on the shaft: remove the back cover if factory-preinstalled, and verify that the outer face of the rotor is at the same depth as the alignment grooves, using a straight edge tool. (Fig 3)

CAUTION

Do not use silicone sealants or caulk of any kind on the motor or encoder face; these can cause misalignment or sensor scraping damage. The XR56 electronics are fully sealed; water may enter and leave the rotor area as needed. A drain hole option is available if frequent moisture buildup is expected.

COVER INSTALLATION

Covers must not interfere with the motor shaft or rotor. The longest shaft that can be used without interfering is 0.72" [18.3mm] with a standard flat cover (Cover Style option "F") and 2.55" [64.8mm] with an extended "pie pan" cover (Cover Style option "E"). Through shaft covers are available for other applications (Cover Style option "T").

EXTENDED COVER MOUNT

(Cover Style option "E")

The extended cover mounts to the encoder housing using quantity 4 #6-32 x 0.31" screws, lock washers, and thread locker.

THRU SHAFT AND FLAT COVER INSTALLATION

(Cover Style option "T" and "F")

The housing has a machined step in the outboard face to accept the cover and a recessed groove for the retaining ring. Insert the cover, line up ears on cover, smooth side facing out, fully into the machined step until it seats against shoulder. Using a spiral assembly method, install the retaining ring by first inserting the squared off end into the machined groove. Flex the ring and insert it into the groove walking it around the perimeter (A flat blade screwdriver can be used). Final position should have the ring fully seated into groove. Remove the cover by reversing above procedure, starting with the tang end.

WIRING

Refer to the attached installation drawings referenced above for wiring diagrams. Use the drawing appropriate for the encoder's installation location. Information on specific connector pin-outs and phasing can be found on labels on the encoders and in the tables included in these instructions.

The XR56 can be wired for single phase or two phase, either with or without complements, with or without markers. For bidirectional operation, Phase A channel typically leads phase B channel for clockwise shaft rotation as viewed from the anti-drive or accessory end of the motor (XR56 mounting end). Refer to the pinout and phasing tables for exceptions.

NOTE

Wiring option "G" provides a pinout compatible with Northstar[™] encoders, with a cable shield connection on pin 10. Note that this option does not ground the shield.

CORRECTIVE ACTION FOR PHASE REVERSAL

- 1) Remove Power.
- 2) Exchange wires on cable, either at encoder cable end, or at speed controller end (but not both).
 - a) Single Ended 2 Phase Wiring (see wiring diagram) Exchange A with B.
 - b) Differential 2 Phase Wiring (see wiring diagram) Exchange either A with A in the phase A pair OR B with B in the phase B pair but NOT both.
- 3) Apply Power.
- Verify encoder feedback is correct, using hand rotation of shaft, or jog mode of the speed controller.

Interconnection cables specified in the wire selection chart are based on typical applications. Cable must be selected and installed in accordance with regional standards. Typical interconnection cable is 4 twisted pair + overall shield. Recommended cable is Avtron B37178. Alternates are Belden P/N 1064A or Rockbestos 04P-18 I/S-OS. Actual cables should be picked based on specific application requirements such as abrasion, temperature, tensile strength, solvents, etc. General electrical requirements are: stranded copper, 20 through 16 AWG, twisted wire pairs, braid or foil individual shields or over-all shield with drain wire, .03uF of maximum total mutual or direct capacitance and outer sheath insulator. 20 AWG wire should not be used for DC power to the encoder for runs greater than 200 feet and 22AWG should not be used for runs greater than 100 ft. This is to minimize voltage drop between the encoder and the XRB3 isolator. The smaller conductors are acceptable for the signal lines.

FAULT-CHECK

After power-up and the rotor position is checked by the sensor, the Fault-Check LED will turn green.

If the adaptive electronics reach their adjustment limit for any reason, the Fault-Check alarm and LED will notify the drive and operator of an impending failure. The LED will turn red if the Adaptive Electronics reach their adjustment limit. This output occurs before an actual failure, allowing steps to be taken to replace the unit before it causes unscheduled downtime. Fault-Check annunciation is available as an "alarm" output through the connector (zone 2 and division 2 configurations only) and as an integral LED.

TROUBLESHOOTING

If the drive indicates a loss of encoder/tach fault and the XR56 faultcheck LED is not illuminated, check the encoder power supply. If power is present, check polarity; one indicator of reversed power supply is that all outputs will be high at the same time. If the drive indicates encoder fault, but the LED shows GREEN, then check the wiring between the drive and the encoder. If the wiring appears correct and in good shape, test the wiring by replacing the XR56. If the new unit shows GREEN, and the drive still shows encoder loss/tach fault, then the wiring is faulty and should be repaired or replaced.

If the alarm output and/or LED indicate a fault (RED):

- 1. Remove the rear cover, and use the built-in gauge to check the location of the rotor (Fig 1). Ensure the label marked "This side out" and/or cam screws is/are facing away from the motor.
- 2. Remove the XR56 from the motor. Clean the housing mounting surface for the XR56 housing. Ensure the XR56 is directly mounted on the motor, with no sealant, gasketing, or other materials, and is firmly bolted in place.

If the alarm output and/or LED indicate a fault (RED) on a properly mounted XR56 and the rotor is properly located, replace the XR56. An oscilloscope can also be used to verify proper output of the SMARTSafe[™] encoder at the encoder connector itself and at the drive/ controller cabinet. If the outputs show large variations in the signals at steady speed (jitter or "accordion effect", see below), check rotor position. If the rotor position is correct, the motor or shaft may be highly magnetized. Replace any magnetized material nearby with non-magnetic material (aluminum, stainless) (especially shafts). For GE CD frame motors and similar styles, Avtron offers non-magnetic stub shafts. If variations persist, consider replacing the encoder with super-shielded models, option -005, or use retrofit shielding kits AVSKxxx yy z, where xxx=model (ex: 56A), yy=rotor (ex: CB), and z=cover (ex: F).

NOTE

Do not use rotors from THIN-LINE I (M56, M56S, M67, M85, M115) with XR56 This will cause incorrect PPR output, but the XR56 LED will remain green.

ENCODER REMOVAL

The XR56 stator housing can be removed by loosening and removing the socket head cap screws.

CAM SCREW ROTOR REMOVAL

Disengage the (2) cam screws by turning them counterclockwise less than 1 full turn. The cam heads will visibly move away from the shaft. Remove the rotor by hand by pulling it away from the motor. If the rotor will not move, do NOT use a gear puller, and do not use a heat gun. Instead, insert two M6 screws, >25mm length into the Jack Screw Holes shown in Fig 2. Alternately tighten the screws to push the rotor away from the motor and remove it.

LARGE BORE SET SCREW ROTOR REMOVAL

Disengage the (2) set screws by turning them counterclockwise until removed from the rotor. Retain the set screws. Remove the rotor by hand by pulling it away from the motor. If the rotor will not move, do NOT use a gear puller, and do not use a heat gun. Instead, pry the rotor away from the motor gently, being careful to only pry against the rotor metal hub and not the magnetic outer strip.



XR56 PA	XR56 PART NUMBERS AND AVAILABLE OPTIONS								
		Style Size							
Model	Housing Type	Rotor Code (See Chart)	Cover Style	Line Driver	Single/Left Output (PPR)	Right Output (PPR)	Connector	Modifications	
XR56A * Set Scre	 Single Output Double Output w Rotor Only 	Co. None-std. Shaft Size XX None US Metric CA- 0.500 D2- 10mm CB- 0.625 D3- 12mm CD- 0.938 DC- 15mm CD- 0.938 DC- 15mm CF- 1.125 D4- 18mm CG- 1.250 DE- 19mm CH- 1.375 DF- 24mm CT- 1.500 DE- 10mm CJ- 1.625 DH- 30mm CK- 1.750 DT- 32mm CJ- 1.625 DH- 30mm CK- 1.750 DT- 32mm CL- 1.875 DH- 30mm CN- 2.200 DM- 45mm CP- 2.375 DN- 48mm CP- 2.350 DP- 52mm TV- 3.004" MU- 60mm* TV-	E- Extended Shaft Cover F- Flat Cover T- Flat Thru- Hole Cover with Shaft Seal	See Line Driver / Connector Options Chart PAGE 5	0- Non- V- 900 std. J- 960 F- 60 Y- 1024 G- 100 Z- 1200 H- 128 4- 2048 L- 240 5- 2500 N- 256 D- 4096 P- 300 8- 4800 E- 360 9- 5000 B- 480 Q- 500 R- 512 S- 600	0- Non-J- 960 std. Y- 1024 F- 60 Z- 1200 G- 100 3- 2000 H- 120 4- 2048 A- 128 5- 2500 L- 240 D- 4096 N- 256 8- 4800 P- 300 9- 5000 E- 360 0- Non- B- 480 Std. R- 512 X- None S- 600 V- 900	See Line Driver / Connector Options Chart	 000- No Modification 005- Super Magnetic Shielding 4xx- Special PPR Code, consult factory 9xx- Special Cable Length, xx=length in feet 018- Includes Isolator 	

SPECIAL PPR OPTION CODES							
OPTION CODE	RIGHT PPR						
401	1270	None					
402	150	None					
403	50	None					
404	512	16					
405	16	None					
406	6000	None					

		Rotor	Codes for E	nglish Shaft	Sizes				Roto	r Codes for N	/letric Shaft	Sizes	
	Cam Scr	ew Style	Set Scre	ew Style	Single Ca	am Keyed] [Cam Scr	ew Style	Set Scr	ew Style	Single Ca	ım Keyed
Size	Rotor	⁻ Code	Rotor	· Code	Rotor	Code		Rotor	Code	Rotoi	⁻ Code	Rotor	Code
Inches	Style	Size	Style	Size	Style	Size	Size mm	Style	Size	Style	Size	Style	Size
NONE	X	X	Х	X	X	х	NONE	Y	х	Y	X	Y	х
0.500	С	Α	Т	Α	к	N/A	10.0	D	2	м	2	J	N/A
0.625	С	В	Т	В	к	N/A	11.0	D	Α	м	Α	J	N/A
0.875	С	С	т	С	к	N/A	12.0	D	3	м	3	J	N/A
0.938	С	D	Т	D	к	D	14.0	D	В	м	В	J	N/A
1.000	С	E	Т	E	к	N/A	15.0	D	с	м	С	J	N/A
1.112	С	3	Т	3	к	N/A	16.0	D	D	м	D	J	N/A
1.125	С	F	Т	F	к	F	18.0	D	4	м	4	J	N/A
1.188	С	2	т	2	к	N/A	19.0	D	E	м	E	J	N/A
1.250	с	G	Т	G	к	N/A	24.0	D	F	м	F	J	N/A
1.375	с	н	Т	н	к	N/A	25.0	D	5	м	5	J	N/A
1.500	С	Т	Т	т	к	N/A	28.0	D	G	м	G	J	N/A
1.625	С	J	т	J	к	N/A	30.0	D	н	м	н	J	N/A
1.750	С	к	т	к	к	N/A	32.0	D	Т	м	т	J	N/A
1.875	с	L	Т	L	к	N/A	36.0	D	J	м	J	J	N/A
2.000	с	м	Т	м	к	N/A	38.0	D	к	м	к	J	N/A
2.125	С	N	Т	N	к	N/A	42.0	D	L	м	L	J	N/A
2.250	С	Q	т	Q	к	N/A	45.0	D	м	м	м	J	N/A
2.375	с	Р	Т	Р	к	N/A	48.0	D	N	м	N	J	N/A
2.500	С	R	Т	R	к	N/A	52.0	D	Р	м	Р	J	N/A
2.625	С	N/A	Т	S	к	N/A	55.0	D	R	м	R	J	N/A
2.750	С	N/A	т	w	к	N/A	60.0	D	S	м	S	J	N/A
2.875	С	N/A	т	U	к	N/A	65.0	D	N/A	м	U	J	N/A
3.000	С	N/A	Т	v	ĸ	N/A	70.0	D	N/A	м	v	J	N/A
3.125	С	N/A	Т	4	к	N/A	75.0	D	N/A	м	w	J	N/A
3.188	С	N/A	Т	7	к	N/A	80.0	D	N/A	м	Y	J	N/A
3.250	с	N/A	Т	z	к	N/A	85.0	D	N/A	м	z	J	N/A

A Nider BRAND

XR56 SMARTSafe[™]

Rev: 09-15-2020

	Line Driver Options						
		Description	ATEX / IECEx Zone 1 & 21	ATEX / IECEx Zone 2 & 22	Class I Div. 1 & Zone 0	Class I Div. 2 Listed	Class I Div. 2 Recognized
		Voltage In / Out	5-7 / 5	5-24 / 5-24	5-7 / 5	5-24 / 5-24	5-24 / 5-24
		Line Driver Code	н	7	F	G	R
	Code	Required Isolator	XRB3	None	XRB3	None	None
	A	10 Pin MS W/O Plug Std Phasing	\checkmark	√	\checkmark		\checkmark
	В	10 Pin MS W/O Plug Dynapar Phasing	\checkmark	√	\checkmark		\checkmark
	с	10 Pin MS W/Plug Std Phasing	\checkmark	√	\checkmark		\checkmark
	D	10 Pin MS W/Plug Dynapar Phasing	~	√	\checkmark		√
	E	7 Pin MS W/Plug A-quad-B Std. Phasing	\checkmark	√	\checkmark		\checkmark
	F	7 Pin MS W/Plug A, A\ Std. Phasing	\checkmark	√	\checkmark		\checkmark
SU	J	7 Pin MS W/Plug A, B, Z Std. Phasing	\checkmark	√	\checkmark		\checkmark
tio	к	7 Pin MS W/Plug A, A B,B\ Std. Phasing	\checkmark	√	\checkmark		\checkmark
0 D	s	7 Pin MS W/Plug A-quad-B Dyn. Phasing	\checkmark	√	\checkmark		\checkmark
tor	т	7 Pin MS W/Plug A, A\ Dyn. Phasing	\checkmark	√	\checkmark		\checkmark
nec	U	7 Pin MS W/Plug A, B, Z Dyn. Phasing	\checkmark	✓	\checkmark		\checkmark
Con	v	7 Pin MS W/Plug A, A B,B\ Dyn. Phasing	\checkmark	✓	\checkmark		\checkmark
) ə(Р	Small Industrial Style Std. Pinout & Plug	\checkmark	√	\checkmark		
inlii	G	Small Industrial Style Northstar Pinout & Plug	\checkmark	√	\checkmark		
Th	R	10 Pin mini Twist Lock with Plug	\checkmark	√	\checkmark		
	w	Flexible Cable with Sealing Gland	\checkmark	√	\checkmark		
	Y	10 Pin MS with Plug on 12" cable	\checkmark	√	\checkmark		
	н	Conduit Box, Terminal Block & 1/2" NPT	\checkmark	√	\checkmark	\checkmark	
	м	Conduit Box, Terminal Block, 3/4" NPT	\checkmark	✓	\checkmark	\checkmark	
	N	Conduit Box, Terminal Block & 1" NPT	\checkmark	✓	\checkmark	\checkmark	
	8	Conduit Box, Terminal Block & 25mm	\checkmark	✓	\checkmark	\checkmark	

SPECIFICATIONS

ELECTRICAL

A. B	Operating Power (Vin) 1. Volts 2. Current	.See Line Driver Option Chart .100mA, each output, no load
υ.	1. 2/ & Comp	A, \overline{A} , \overline{B} , \overline{B} (differential line driver)
C. D.	Signal Type Direction Sensing	Incremental, Square Wave, 50 ±10% Duty Cycle.
		Refer to the connector pinout and phasing table for exceptions B for CW rotation as viewed from the back of the tach looking at the non-drive end of the motor.
E.	Phase Sep	.15% minimum
г. G.	PPR	.8-5000 H2
Η.	Line Driver Specs	See table
ı. J.	Integral LED Indicator	.See connector options on page 1 .GREEN: power on, unit ok, RED: alarm on
•••		
M	ECHANICAL	
A. B. C. D. E.	Rotor Inertia Acceleration Speed Weight Sensor to Rotor	.0.17-0.36 Oz. In. Sec.2 .5000 RPM/Sec. Max. .5400 RPM Max. .2-3 lbs [0.9kg to 1.36kg].

Rotor Inertia	0.17-0.36 Oz. In. Sec.2	
Acceleration	5000 RPM/Sec. Max.	
Speed	5400 RPM Max.	
Weight	2-3 lbs [0.9kg to 1.36kg].	
Sensor to Rotor		
Air Gap (nominal)	0.023" [0.58mm]	
Tolerance	±0.015" [0.38mm]	
D. A. L. L.T. L	0.050"[4.07]	

F. Rotor Axial Tolerance......±0.050" [±1.27mm]

ENVIRONMENTAL

Solid cast aluminum stator and rotor. Less than 7.5% in total magnesium, titanium and zirconium. Fully potted electronics, protected against oil and water spray. Operating Temperature: -40 to 80°C, 0-100% condensing humidity. See "Description" section for information on hazardous location environments.

XR56 Connector Spare Parts							
Style	Code	Enco	der Side	Customer Side			
Small		315934	Base	315937	Hood		
Industrial	P, G	315935	Terminals	315936	Terminals		
"Epic"				401122	1/2 NPT		
		431079	Receptacle	316445	Plug		
				411216	Bushing		
10 pin MS	A, B, C, D			411217	Bushing		
				411218	Bushing		
				411219	Bushing		
	FFIN	431080	Receptacle	316446	Plug		
7 Pin MS	е, г, ј, к, S, T, U, V			411218	Bushing		
				411219	Bushing		
Conduit	HMN8			364987	Terminal		
Box	11,101,10,0			504507	Plug		
10 pin		431081	Base				
mini MS	R	451001	Dase	316447	Plua		
Twist Lock		471748	Gasket				
		314383	In-Line	316445	Plug		
10 pip MS				411216	Bushing		
on cable	Y			411217	Bushing		
on cable				411218	Bushing		
				411219	Bushing		

				Line Driver	Specifications		Isolator Specifications	
Code			Н	7	F	G	XRB3	
	Description	Symbol	ATEX / IECEx Zone 1 & 21(ia)	ATEX / IECEx Zone 2 & 22	Class I Div. 1 & Zone 0	Class I Div. 2 Listed	ATEX/IECEx Zone 1&21(ia) + Class I Div 1&Zone 0	Units
Line Driver			7272	7272	7272	7272	IXDF604	
Input \	/oltage (Nominal)	V _{IN} / V _S	5-7	5-24	5-7	5-24	12-24	V _{DC}
Input V	/oltage (Max Safe)	UM	N/A	N/A	N/A	N/A	30	V
Input	Current (no load)	l _{in} / ls	80	80	80	80	150	mA
Input	Current (Typical)	l _{in} / ls	100	200	100	200	450	mA
Input	t Current (Max.)	l _{IN} / ls	140	300	140	300	900	mA
Output	Voltage (nominal)	V _H	N/A	N/A	N/A	N/A	6.8	V _{DC}
Output Vo	ltage Min.(@140mA)	V _H	N/A	N/A	N/A	N/A	5	V _{DC}
Output Vo	oltabe Max(No Load)	V _H	N/A	N/A	N/A	N/A	7.14	V _{DC}
Output Current (@6.8V)		IH	N/A	N/A	N/A	N/A	115	mA
Output Current (@5V)		Iн	N/A	N/A	N/A	N/A	140	mA
Output C	urrent (short circuit)	Iн	N/A	N/A	N/A	N/A	420	mA
Voltage O	utput High (Nominal)	V _{он}	5	V _{IN} -1	5	V _{IN} -1	Vs-1	V _{DC}
Voltage O	utput Low (Nominal)	V _{OL}	.5	.5	.5	.5	.4	V _{DC}
Signal Cu	urrent (Continuous)	I _{OH} / I _{OL}	100	100	100	100	2580	mA
Signa	al Current (Peak)	I _{OH} / I _{OL}	1500	1500	1500	1500	3000	mA
Outp	out Resistance Ω	R _{OH} / R _{OL}	15	15	15	15	7	Ω
	Cable Drive		500	5-15Vin=500 24Vin = 250	500	5-15Vin=500 24Vin = 250	1000	ft.
	Reverse Voltage		Yes	Yes	Yes	Yes	Yes	
Protection	Short Circuit		Best	Good	Best	Good	Best	
	Transient		Good	Good	Good	Good	Best	
	+Vout		no	Yes	no	Yes	no	
	Alarm		no	Yes	no	Yes	no	
Alarma	LED		Yes	Yes	Yes	Yes	Yes	
Aldrin	+Vout		Reverence Signal for	r Alarm Circuit, Outp	ut Voltage = Input Vol	tage		
	Alarm		Open Collector, nor	mally off, goes low or	n alarm, sink 100mA n	nax, See Connecto	r Pinouts for Availability	
	LED		Green = Power On.	Red = Alarm				

Thinline II Spare Parts (XR56/XR56S/XR67/XR85/XR115 Only) SAE/USA Sizes								
	Rot XR56, XR5 XR	tors 6S, XR67 & 115	Rotor AV56S & XR56S	Thru-Shaft Covers				
Shaft Size	Option Code	Cam Screw	Set Screw Stainless Rotor	AV56, AV56S, AV67, AV115, XR56, XR56S, XR67 & XR115 Cover Kit	AV85/XR85 Cover /kit			
.500/.4995	CA	AVTR1-CA	AVTR2-TA	A36521-TA	A36523-TA			
.625/.6245	СВ	AVTR1-CB	AVTR2-TB	A36521-TB	A36523-TB			
.875/.8745	CC	AVTR1-CC	AVTR2-TC	A36521-TC	A36523-TC			
.9375/.9370	CD	AVTR1-CD	AVTR2-TD	A36521-TD	A36523-TD			
1.000/.9995	CE	AVTR1-CE	AVTR2-TE	A36521-TE	A36523-TE			
1.125/1.1245	CF	AVTR1-CF	AVTR2-TF	A36521-TF	A36523-TF			
1.250/1.2495	CG	AVTR1-CG	AVTR2-TG	A36521-TG	A36523-TG			
1.375/1.3745	СН	AVTR1-CH	AVTR2-TH	A36521-TH	A36523-TH			
1.500/1.4995	СТ	AVTR1-CT	AVTR2-TT	A36521-TT	A36523-TT			
1.625/1.6245	CJ	AVTR1-CJ	AVTR2-TJ	A36521-TJ	A36523-TJ			
1.750/1.7495	СК	AVTR1-CK	AVTR2-TK	A36521-TK	A36523-TK			
1.875/1.8745	CL	AVTR1-CL	AVTR2-TL	A36521-TL	A36523-TL			
2.000/1.9995	СМ	AVTR1-CM	AVTR2-TM	A36521-TM	A36523-TM			
2.125/2.1245	CN	AVTR1-CN	AVTR2-TN	A36521-TN	A36523-TN			
2.250/2.2495	CQ	AVTR1-CQ	AVTR2-TQ	A36521-TQ	A36523-TQ			
2.375/2.3745	CP	AVTR1-CP	AVTR2-TP	A36521-TP	A36523-TP			
2.500/2.4995	CR	AVTR1-CR	AVTR2-TR	A36521-TR	A36523-TR			
2.625/2.6245	TS	N/A	AVTR2-TS	A36521-TS	A36523-TS			
2.875/2.8745	TU	N/A	AVTR2-TU	A36521-TU	A36523-TU			
3.000/2.9995	TV	N/A	AVTR2-TV	A36521-TV	A36523-TV			
3.1250/3.1245	T4	N/A	AVTR2-T4	A36737-T4	A36523-T4			
3.1875/3.1870	T7	N/A	AVTR2-T7	A36737-T7	A36523-T7			

1.125" w/.25" Keyway	AVTR-KD
15/16" w/.25" Keyway	AVTR-KF

Extended and Flat Cover Plates									
Shaft Size	Model	Extended Shaft Cover Kit	Flat Cover Kit						
Any	AV56A, AV67, AV115, XR56A, XR67, XR115	A35841	A37298						
Any	AV56S, XR56S	A36526	A37298						
Any	AV85, XR85	A35841	A36525						

Thinline II Spare Parts											
(XR56/XR56S/XR67/XR85/XR115 Only)											
Metric Sizes											
	R	otors XR5	6 A .								
	XR6	7, XR85,)	(R115	Thru-Shaft Covers							
Shaft Size	Option Code	Cam Screw	Set Screw	AV56, AV56S, AV67, AV115, XR56, XR56S, XR67, XR115, Cover Kit	AV85/XR85 Cover /kit						
10mm	D2	AVTR1-D2	N/A	A36522-M2	A36524-M2						
11mm	DA	AVTR1-DA	N/A	A36522-MA	A36524-MA						
12mm	D3	AVTR1-D3	N/A	A36522-M3	A36524-M3						
14mm	DB	AVTR1-DB	N/A	A36522-MB	A36524-MB						
15mm	DC	AVTR1-DC	N/A	A36522-MC	A36524-MC						
16mm	DD	AVTR1-DD	N/A	A36522-MD	A36524-MD						
18mm	D4	AVTR1-D4	N/A	A36522-M4	A36524-M4						
19mm	DE	AVTR1-DE	N/A	A36522-ME	A36524-ME						
24mm	DF	AVTR1-DF	N/A	A36522-MF	A36524-MF						
28mm	DG	AVTR1-DG	N/A	A36522-MG	A36524-MG						
30mm	DH	AVTR1-DH	N/A	A36522-MH	A36524-MH						
32mm	DT	AVTR1-DT	N/A	A36522-MT	A36524-MT						
36mm	DJ	AVTR1-DJ	N/A	A36522-MJ	A36524-MJ						
38mm	DK	AVTR1-DK	N/A	A36522-MK	A36524-MK						
42mm	DL	AVTR1-DL	N/A	A36522-ML	A36524-ML						
45mm	DM	AVTR1-DM	N/A	A36522-MM	A36524-MM						
48mm	DN	AVTR1-DN	N/A	A36522-MN	A36524-MN						
52mm	DP	AVTR1-DP	N/A	A36522-MP	A36524-MP						
55mm	DR	AVTR1-DR	N/A	A36522-MR	A36524-MR						
60mm	DS	AVTR1-DS	N/A	A36522-MS	A36524-MS						
65mm	MU	N/A	AVTR1-MU	A36522-MU	A36524-MU						
70mm	MV	N/A	AVTR1-MV	A36522-MV	A36524-MV						
75mm	MW	N/A	AVTR1-MW	A36522-MW	A36524-MW						
80mm	MY	N/A	AVTR1-MY	A36737-MY	A36524-MY						
85mm	MZ	N/A	AVTR1-MZ	A36737-MZ	A36524-MZ						



See the following Control Drawings for Wiring Information

D53008: ATEX / IECEx Zone 1 & 21

D52353: ATEX / IECEx Zone 2 & 22

D52354: Division 1

D52355: Division 2

Pinouts for Connector Options

Connection]				-							-	
Option Code	Description	Phasing	Signal	0V Gnd	A+	B+	Z+	* Alm+	+Vin		 B-		* Alm
Y	10 Pin MS Avtron / Northstar Pinout	CW	Pin #	А	D	E	С	NC	В	G	Н	I	NC
A,C	10 Pin MS Small Encoder Std Pinout	CW	Pin #	F	Α	В	С	NC	D	Н	Ι	J	NC
B,D	10 Pin MS Small Encoder Dynapar Pinout	CCW	Pin #	F	Α	В	С	NC	D	Н	Ι	J	NC
R	10 Pin MS Mini Twist Lock	CW	Pin #	F	Α	В	С	NC	D	Н	J	K	NC
Р	10 Pin, Mini Industrial, Avtron Pinout	CW	Pin #	1	2	3	4	5	6	7	8	9	10
G	10 Pin, Mini Industrial, Northstar Pinout	CW	Pin #	1	2	3	4	NC	6	7	8	9	NC
H,M,N,8	Conduit Box W/10 Pin Terminal Block	CW	Pin #	1	2	3	4	5	6	7	8	9	10
W	10 Conductor Wire Cable	CW	Color	BLK	GRN	BLU	ORG	BRN	RED	YEL	GRA	WHT	VIO

* Remote alarm function only connected for Zone 2, Zone 22 and Division 2

Connection											
Option Code	Description	Phasing	Signal	0V Gnd	A+	B+	Z+	+Vin	A-	 B-	
К	7 Pin MS, Avtron / BEI Pinout (A,AB,B\)	CW	Pin #	F	Α	В	NC	D	С	Е	NC
F	7 Pin MS, Avtron / BEI Pinout (A,A\)	CW	Pin #	F	А	NC	NC	D	C	NC	NC
J	7 Pin MS, Avtron / BEI Pinout (A,B,Z)	CW	Pin #	F	А	В	С	D	NC	NC	NC
E	7 Pin MS, Avtron / BEI Pinout (A,B)	CW	Pin #	F	А	В	NC	D	NC	NC	NC
V	7 Pin MS, Dynapar Pinout (A,AB,B\)	CCW	Pin #	F	А	В	NC	D	C	Е	NC
Т	7 Pin MS, Dynapar HS35 Pinout (A,A\)	CCW	Pin #	F	А	NC	NC	D	C	NC	NC
U	7 Pin MS, Dynapar HS35 Pinout (A,B,Z)	CCW	Pin #	F	A	В	C	D	NC	NC	NC
S	7 Pin MS, Dynapar HS35 Pinout (A,B)	CCW	Pin #	F	A	В	NC	D	NC	NC	NC

Phasing is defined as the direction of rotation for which phase A leads B as viewed from the back of the Encoder

THIN-LINE II™

Application Examples

Applies to XR56 Zone 2 & Division 2 models, with wiring options "W", "P", "H", "M","N", and "8". Remote alarm not available for Zone I & Div I

ALARM OUTPUT CONNECTION

Avtron THIN-LINE II encoders provide an alarm signal if maintenance is required under specific circumstances. An alarm LED indicator is also available. Green indicates power on, red indicates alarm on. Following are application examples provided to help install the alarm output.

Example 1. Alarm output using +V(OUT). +V(OUT) is equal to +V, the encoder power supply.



Example 2. Alarm output using seperate *VDC power supply and relay.



XR56 SMARTSafe[™]



1 – WEIGHT: 2.5 - 4LBS [1.13 TO 1.81 KG].

Company Name ------

Authorized Company Representative_

Title

— Date —

Features and specifications subject to change without notice. Avtron standard warranty applies. All dimensions are in Inches [mm] approx. $\ensuremath{\mathsf{CE}}$

Nidec Industrial Solutions | 243 Tuxedo Avenue | Cleveland, Ohio 44131 | encoderhelpdesk@nidec-industrial.com +1 216-642-1230 | www.avtronencoders.com

XR56 SMARTSafe[™]



XR56

7R56 14

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UNLESS OTHERWISE SPECIFIED THE ABOVE NOTES APPLY

TINNED.

CAUTION: BE SURE TO REMOVE POWER BEFORE WRING THE ENCODER. GROUND GROUND LUG FOR CUSTOMER CONVENIENCE AND ENCODER FRAME GROUNDING WITH ' INTERCONNECTION CABLES SPECIFIED ARE BASED ON TYPICAL APPLICATIONS. CABLE CANADIAN ELECTRICAL REQUIREMENTS ARE: STRANDED COPPER, 20 THROUCH 16 AWG GENERAL ELECTRICAL REQUIREMENTS ARE: STRANDED COPPER, 20 THROUCH 16 AWG FOIL INDIVIDUAL SHIELDS OR OVER ALL SHIELD WITH DRAIN WRE, 0.050°F OF MAXIMU FOIL INDIVIDUAL SHIELDS OR OVER ALL SHIELD WITH DRAIN WRE, 0.050°F OF MAXIMU

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SPECIAL CONDITIONS FOR SAFE USE:

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