

www.avtronencoders.com

Nidec Industrial Solutions 243 Tuxedo Avenue | Cleveland, Ohio 44131

encoderhelpdesk@nidec-industrial.com +1 216-642-1230

ENCODER INSTRUCTIONS

DESCRIPTION

The Avtron Model XR685 SMARTSafe[™] is a severe duty incremental encoder for use in hazardous locations (also known as tachometer or rotary pulse generator). Its output is directly proportional to shaft position (pulse count) or speed (pulse rate). The XR685 operates down to zero speed and can be used for both control and instrumentation applications.

CAUTION

The XR685 is designed for use in hazardous applications which require protection from gas or dust ignition for safe operation. Proper selection, wiring and installation procedures are essential to ensuring safe conditions.

When mounted to a machine shaft, the XR685 design eliminates the need for shaft couplings, adapter flanges, or accessory mounting faces. The unit employs a keyless shaft mount to lock the XR685's rotor to a 1.125" diameter shaft. An anti-rotation arm prevents housing rotation while allowing for shaft end float.

The XR685 utilizes magnetoresistive sensors. This proven technology is ideal for rugged environments since it is immune to many contaminants that cause optical encoders to fail. These factors make the XR685 ideal for demanding industries like paper, metals, and chemical processing.

The outputs are protected against short circuits and wiring errors. An Avtron XR685 SMARTSafe encoder is equipped with one or two XR5 sensor modules. Each module has a two-phase output (A, B) 90° out of phase, with complements $(\overline{A}, \overline{B})$, (A Quad B Output). A marker pulse with complement (Z, \overline{Z}) is also present.

Output resolution on the XR685 is determined by the sensor only. Unlike older models, any PPRs can be mixed and matched. Selection of the rotor is based only on the shaft mounting requirements (and not PPR).

The XR5 removable sensor assembly has a diagnostic package that includes Adaptive Electronics and a Fault-Check output.

ADAPTIVE ELECTRONICS

A perfect duty cycle consists of a waveform whose "high" and "low" conditions are of the same duration (50%/50%). It is possible over time for the duty cycle and edge separation to change due to component drift, temperature changes, or mechanical wear. The Adaptive Electronics extend the life of the XR685 by constantly monitoring and correcting duty cycle and edge separation over time.



INSTALLATION

CAUTION

Be careful not to damage clamping fingers of hollow shaft during handling. Do not tighten clamping collar before installation onto motor shaft.

WARNING

Installation should be performed only by qualified personnel. Safety precautions must be taken to ensure machinery cannot rotate and all sources of power are removed during installation.

Refer to the following attached installation drawings for installation information appropriate for specific hazardous locations: D53008: ATEX / IECEx Zone 1, 21 D52353: ATEX / IECEx Zone 2, 22 D52354: US and Canada Class I Division 1 Encoder D52355: US and Canada Class I Division 2

NOTE:

The equipment is intended for a fixed installation and should be mounted so as to avoid electrostatic charging. The XR45 is not considered as a safety device and is not suitable for connection into a safety system.

The XR685 construction materials contain less than 7.5% in total by mass of magnesium, titanium and zirconium. These materials are not considered as able to trigger an explosion in normal operating modes. These materials are not known to react with any explosive atmospheres to which the XR685 may be subject. It is however the responsibility of the end user to ensure that the XR685 is selected correctly for the potentially explosive atmosphere in which the equipment is to be put into service.

Equipment needed for installation

Supplied:

2.

- XR685 Encoder 1.
 - 4. Synthetic Grease Anti-Rotation Arm Kit 5. Anti-Seize (copper)
- 3. Thread Locker (blue)

Not Supplied:

1-3/4" Clator Nut Wrench (484017) 2-1/2" Locking Nut Wrench (484018) 7/16" Wrench 1/2" Wrench **Dial Indicator** Model XRB3 Isolator for Division 1, Zone 0,1, 20 and 21 applications (Sold Separately)

XR685 SMARTSafe[™]

The hollow shaft XR685 design eliminates the potential for bearing and coupling failures from misalignment, however, excessive housing movement (wobble) may cause undesirable vibrations. The higher the RPM, the more severe the vibration will be from housing movement. In a typical installation a housing movement of 0.007" TIR or less (as measured at the outside diameter of the main encoder body) will not have an adverse effect.

MACHINE SHAFT PREPARATION

Preparing the machine shaft prior to encoder installation is essential in providing an adequate barrier against environmental contamination. In some cases, a separate stub shaft (1.125" D x 4.5" long) will be installed on the motor. To prepare the machine shaft that the XR685 is to be installed on, conduct the following procedures (see figures):

- 1) Remove from the XR685 the four 1/4-20 UNC machine screws which hold the end cap on the cover plate.
- 2) Remove the end cap, O-Ring, and wave spring, noting the location of each to assist in re-assembly.

Caution

Spanner wrenches must be used during the following procedures. Using a substitute can distort the 1-3/4" nut and damage the unit. Do not try to remove the larger 2-1/2" bearing locknut at any time. This locknut is factory adjusted for optimum XR685 performance.

NOTE

Two spanner wrenches, which are required for XR685 installation, accommodate the 1-3/4" and 2-1/2" nuts found under the cap.

- 3) Holding the 2-1/2" bearing locknut, remove the 1-3/4" dia. clamping nut and slide out the internal compression sleeve.
- 4) Verify that the compression sleeve can be installed by hand on the shaft where the unit is to be installed. File any burrs that obstruct sleeve installation and lightly oil the shaft.
- If a keyway or flat exists on the shaft, provide a sealing medium, or true the shaft back to round using metal putty or equal.
- 6) Return the compression sleeve to the XR685 hub.
- 7) Thread the 1-3/4" clamping nut onto the XR685 by hand until resistance is felt. DO NOT TIGHTEN at this time.

ENCODER INSTALLATION

Installing the XR685 and Anti-Rotation Arm:

- The free end of the anti-rotation arm must be secured by the customer to a stationary member such as the floor or machine frame. Refer to "Anti-Rotation Arm Mounting Guidelines" on the last page for general requirements.
- Based on the location of the stationary point and the guidelines on page 6, attach the 1/4" thick mounting board to one of two places on the XR685. Use two 1/4-20 UNC by 3/4" long machine screws provided.
- 3) Apply anti-seize (copper), provided, to machine shaft. A packet of silicone grease is provided to lubricate the following shaft seals: First, ALL XR685 types have an 0-Ring inside their hollow shafts at the motor end. In addition, in THRU-SHAFT types, the clamping nut has an 0-Ring on the inside, plus the outside of the clamping nut requires lubrication for the radial lip seal per step 8b. Slide the XR685 onto the machine shaft, mounting the board first. Ideally, the XR685 housing will be 1/2" to 1" from the motor or machine housing, but this may vary depending on the machine profile and the anti-rotation arm clearance requirements. Consider shaft end float when positioning the XR685.
- 4a) FOR END-of-SHAFT APPLICATIONS, place the XR685 3.38" to 4.13" onto the shaft. The end of the machine shaft must extend completely through the XR685 compression sleeve and be approximately flush with the end of the 1-3/4" clamping nut.
- 4b) FOR THRU SHAFT APPLICATIONS, position the XR685 as required.

- 5) Attach free end of the anti-rotation arm to the 1/4" mounting board using the shoulder bolt provided.
- 6) Remove 1-3/4" clamping nut and apply liquid thread locker to the threads. (Locktite grade 242, supplied, should be used in most applications.)
- 7) Replace 1-3/4" clamping nut and tighten so the gap is less than or equal to 0.09", as shown in CLAMPING NUT sketch (approx. 15-20 ft-lbs.), holding the 2-1/2" bearing locknut in place. Spanner wrenches are required for this operation.
- 8a) FOR END-of-SHAFT INSTALLATIONS, replace the end cap with the wave spring (loading spring) against the bearing and the O-ring located in the cap groove. Secure the end cap with the four 1/4-20 UNC machine screws previously removed. Apply the thread locker to the screws when assembling.
- 8b) FOR THRU SHAFT APPLICATIONS, prior to replacing the end cap per step 8a, apply a small amount of silicone grease (provided) to the seal surface on the 1-3/4" clamping nut. The radial lip seal in the end cap will seal on this surface.

ENVIRONMENTAL CONSIDERATIONS

Special attention is to be given to conduit runs, interconnection wiring and NEMA type enclosure mounting. In those applications where ambient temperatures are controlled within 20° C and high humidity/ washdown are not present, position the flexible conduit with a slight sag to prevent any condensation from entering the encoder via conduit.

In harsh environments, which include temperature extremes, high humidity, equipment washdown or atmosphere contamination, extra care is required. Follow these steps to reduce potential problems:

- 1) Always mount connection points, conduit couplings, junction boxes, etc., lower than actual encoder.
- 2) For washdown areas, shroud or otherwise cover the encoder to prevent direct water spray. Do not attach the shroud directly to the encoder.
- 3) Keep conduit outputs and axis of rotation horizontal.
- Avtron recommends sealed and/or remote connector styles for these applications. These include options (A-J, M-N, R-T, W, Y).

ANTI-ROTATION ARM MOUNTING GUIDELINES

The anti-rotation arm stabilizes the encoder and keeps it from rotating as the machine shaft rotates. To get the best performance, minimize generator movement by following these anti-rotation arm mounting guidelines as closely as possible.

- 1) Mount XR685 with conduit entry ports positioned horizontally.
- Fasten the 1/4" thick mounting board to the inboard side of the XR685 in one of the two positions shown. Use the two 1/4-20 UNC x 3/4" long fasteners.
- Mount anti-rotation arm perpendicular to motor shaft axis of rotation. Arm mounting bolts and associated rod bearings should be parallel to motor shaft also (top view).
- Mount anti-rotation arm approx. 90° to a line established between the mounting board mounting hole and shaft centerline (viewed from end).
- Mount XR685 as close as possible to the motor with the mounting board closest to the motor.
- Establish a stationary (static) mounting point for the free end of the anti-rotation arm, using the guidelines above. Use the bolt provided to fasten arm to stationary point.
- 7) The anti-rotation arm is fully threaded and can be adjusted in length. The recommended length is 8 to 12".

WIRING INSTRUCTIONS

Refer to the attached installation drawings referenced above for wiring diagrams. Use the drawing appropriate for the encoder's installation location. Information on specific connector pin-outs and phasing can be found on labels on the encoders and in the tables included in these instructions.

The XR685 can be wired for single phase or two phase, either with or without complements, with or without markers. For bidirectional operation, in most cases Phase A channel typically leads phase B channel for clockwise shaft rotation as viewed from the anti-drive or accessory end of the motor. See pinout and phasing tables for exceptions.

Wiring option "G" provides a pinout compatible with Northstar encoders, with a cable shield connection on pin 10. Note that this option does not ground the shield.

CORRECTIVE ACTION FOR PHASE REVERSAL

1) Remove Power.

- 2) Exchange wires on cable, either at encoder cable end, or at speed controller end (but not both).
 - a) Single Ended 2 Phase Wiring (see wiring diagram) Exchange A and B at the use end of the wires.
 - b) Differential 2 Phase Wiring (see wiring diagram)
 Exchange either A with A- in the phase A pair OR B with B- in the phase B pair but NOT both.
- 3) Apply Power.
- Verify encoder feedback is correct, using hand rotation of shaft, or jog mode of the speed controller.

Interconnection cables specified in the wire selection chart are based on typical applications. Cable must be selected and installed in accordance with regional standards. Typical interconnection cable is 4 twisted pair + overall shield. Recommended cable is Avtron B37178. Alternates are Belden P/N 1064A or Rockbestos 04P-18 I/S-0S. Actual cables should be picked based on specific application requirements such as abrasion, temperature, tensile strength, solvents, etc. General electrical requirements are: stranded copper, 20 through 16 AWG, twisted wire pairs, braid or foil individual shields or over-all shield with drain wire, .03uF of maximum total mutual or direct capacitance and outer sheath insulator. 20 AWG wire should not be used for DC power to the encoder for runs greater than 200 feet and 22AWG should not be used for runs greater than 100 ft. This is to minimize voltage drop between the encoder and the XRB3 isolator. The smaller conductors are acceptable for the signal lines.

NOTE

When using the industrial connector ("G" and "P" options), the minimum wire size is 20 gauge, and 20 gauge (only) wire ends must be tinned with solder before connection at the screw terminals.

MAINTENANCE

GENERAL

This section describes routine maintenance for the Avtron XR685 Encoder. For support, contact Avtron's field service department at 216-642-1230. For emergency after hours service contact us at 216-641-8317.

FAULT-CHECK

After power-up and the internal rotor position is checked by the sensor, the Fault-Check LED will turn green.

If the adaptive electronics reach their adjustment limit for any reason, the Fault-Check alarm and LED will notify the drive and operator of an impending failure. The LED will turn red if the Adaptive Electronics reach their adjustment limit. This output occurs before an actual failure, allowing steps to be taken to replace the unit before it causes unscheduled downtime. Fault-Check annunciation is available as an "alarm" output through the connector (zone 2 configurations only) and as an integral LED.

TROUBLESHOOTING:

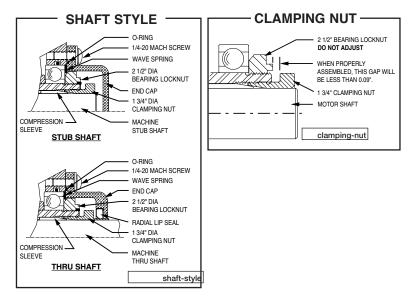
If the drive indicates a loss of encoder/tach fault and the XR685 faultcheck LED is not illuminated, check the encoder power supply. If power is present, check polarity: one indicator of reversed power supply is that all outputs will be high at the same time. If the drive indicates encoder fault, but the LED shows GREEN, then check the wiring between the drive and the encoder. If the wiring appears correct and in good shape, test the wiring by replacing the XR5 sensor module. If the new module shows GREEN, and the drive still shows encoder loss/tach fault, then the wiring is faulty and should be repaired or replaced.

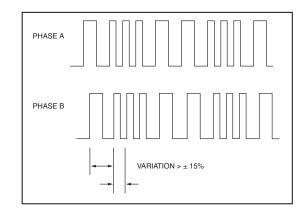
If the alarm output and/or LED indicate a fault (RED):

- 1. Remove an end sensor plate or the second sensor, and use the built-in gauge to check the location of the rotor (see Figure 1).
- Remove the XR5 sensor from the housing. Clean the housing mounting surface for the XR5 sensor and the XR685 housing. If the alarm output and/or LED indicate a fault (RED) on a properly mounted XR5 sensor and the rotor is properly located, replace the XR5 sensor.

An oscilloscope can also be used to verify proper output of the XR5 encoder at the encoder connector itself and at the drive/controller cabinet.

If the outputs show large variations in the signals at steady speed (jitter or "accordion effect", See figure below), check rotor position. If the rotor position is correct, the motor or shaft may be highly magnetized. Replace any magnetized shafts with non-magnetic material (stainless/ aluminum). Consider replacing the sensors with super-shielded models, option -004.





XR685 PART NUMBERS AND AVAILABLE OPTIONS INCLUDING AV5 SENSORS												
Model	Temp Rating	Tether	Style	Lef Line Driver	t Module PPR	Rig Line Driver	ht Module PPR	Connector Options	Modifi- cations			
acces	N20°C to 80°C C40°C to 80°C sensors and sories can be id separately. able 2.	X- none 1- B21958 threaded rod	E- standard (EOS) T- through shaft	See Line Driver / Connector Options Chart	X- none 6- 1800 F- 60 3- 2000 G- 100 4- 2048 H- 120 5- 2500 A- 128 D- 4096 L- 240 8- 4800 N- 256 9- 5000 P- 300 0- special E- 360 B- 480 Q- 500 R- 512 S- 600 V- 900 J- 960 Y- 1024 Z- 1200	See Line Driver / Connector Options Chart	$\begin{array}{rrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrr$	See Line Driver / Connector Options Chart	000- none 004- Super Magnetic Shielding 97mm Rotor 400- Special PPR (see table) 018- Includes isolator 900- Special Cable Length (xx=ff/0.3m)			

				Modifications		
Model	Line Driver	PPR	Connector Options			
XR5-	See Line Driver Connection Option Chart	X- none S- 600 F- 60 V- 900 G- 100 J- 960 H- 120 Y- 1024 A- 128 Z- 1200 L- 240 3- 2000 N- 256 4- 2048 P- 300 5- 2500 E- 360 D- 4096 B- 480 8- 4800 Q- 500 9- 5000 R- 512 0-special	See Line Driver Connection Option Chart	000- none 004- Super Magnetic Shielding 005- Special 97mm Rotor (see special manual) 4xx- Special PPR (see table) 9xx- Special Cable Length (xx=ff/0.3m)		

SPECIAL PPR OPTION CODES										
OPTION CODE	LEFT PPR	RIGHT PPR								
401	1270	None								
402	150	None								
403	50	None								
404	512	16								
405	16	None								
406	6000	None								

			Line Driver Options									
		Description	ATEX / IECEx Zone 1 & 21	ATEX / IECEx Zone 2 & 22	Class Div. 1 & Zone 0	Class I Div. 2 Listed	Class I Div. 2 Recognized					
		Voltage In / Out	5-7 / 5	5-24 / 5-24	5-7 / 5	5-24 / 5-24	5-24 / 5-24					
		Line Driver Code	Н	7	F	G	R					
	Code	Required Isolator	XRB3	None	XRB3	None	None					
	А	10 Pin MS W/O Plug	\checkmark	✓	\checkmark		\checkmark					
	В	10 Pin MS With Plug	\checkmark	✓	\checkmark		\checkmark					
	Е	7 Pin MS W/Plug A-quad-B Std. Phasing	~	~	\checkmark		\checkmark					
S	F	7 Pin MS W/Plug A, A\ Std. Phasing	\checkmark	~	\checkmark		\checkmark					
on	J	7 Pin MS W/Plug A, B, Z Std. Phasing	\checkmark	~	\checkmark		\checkmark					
pti	К	7 Pin MS W/Plug A, A B,B\ Std. Phasing	\checkmark	~	\checkmark		\checkmark					
r O	S	7 Pin MS W/Plug A-quad-B Dyn. Phasing	~	~	\checkmark		\checkmark					
cto	Т	7 Pin MS W/Plug A, A\ Dyn. Phasing	~	~	\checkmark		\checkmark					
nec	U	7 Pin MS W/Plug A, B, Z Dyn. Phasing	~	~	\checkmark		\checkmark					
on	۷	7 Pin MS W/Plug A, A B,B\ Dyn. Phasing	~	~	\checkmark		✓					
U U U	Р	Large Industrial Style Std. Pinout & Plug	~	~	\checkmark							
acl	G	Large Industrial Style Northstar Pinout & Plug	~	~	\checkmark							
SMARTach Connector Options	R	10 Pin mini Twist Lock with Plug	~	~	~							
MA	W	Flexible Cable with Sealing Gland	~	~	\checkmark							
S	4	Conduit Box, Terminal Block & 1/2" NPT	~	~	\checkmark	✓						
	5	Conduit Box, Terminal Block, 3/4" NPT+Cord	~	~	\checkmark	✓						
	6	Conduit Box, Terminal Block & 1" NPT	~	~	\checkmark	✓						
	7	Conduit Box, Terminal Block & 25mm	~	~	~	✓						

SPECIFICATIONS

ELECTRICAL

Δ	Operating	Power	(\/ir

2. Current	See Line Driver Option Chart Each output, 100mA Nom. 355mA Max.
B. Output Format	A, A, B, B (differential line driver)
2. Marker	
C. Signal Type	Incremental, Square Wave, 50 ±10% Duty Cycle.
D. Direction Sensing	Ø A leads Ø B for CW rotation as viewed from
	the back of the tach looking at the non-drive end
	of the motor.
E. Phase Sep	15% minimum
F. Frequency Range	0 to 165,000 Hz
G. PPR	8-5000
H. Line Driver Specs	See table
I. Connectors	See connector options on page 1
J. Integral LED Indicator	GREEN: power on, unit ok. RED: alarm on
5	

MECHANICAL

A. Shaft Inertia	25 Oz. In. Sec. ²
B. Acceleration	5000 RPM/Sec. Max.
C. Speed	5400 RPM Max.
D. Weight	

ENVIRONMENTAL

Solid cast aluminum stator and rotor 7.5% of magnesium, titanium and zirconium total by mass Fully ported electronics, protected against oil and water spray operating temp see rating on P/N chart See "Description" section for information on hazardous location environments

XR685 Connector Spare Parts									
Style	Code	Ene	coder Side	Cus	tomer Side				
Large		314879	Base	314880	Hood				
Industrial	P, G	314878	Terminals	314877	Terminals				
"Epic"									
	А, В	Box	Recepticle		Plug				
		315933	Standard	315932	Standard				
		431079	Line Driver "R"	316445	Line Driver "R"				
10 pin MS				411216	Bushing				
				411217	Bushing				
				411218	Bushing				
				411219	Bushing				
		Вох	Recepticle		Plug				
		316297	Standard	315932	Standard				
7 Pin MS	E, F, J, K, S, T, U, V	431080	Line Driver "R"	316446	Line Driver "R"				
	-, ., -, .			411218	Bushing				
				411219	Bushing				
Conduit Box	4,5,6,7			364987	Terminal Plug				
10 pin mini MS	R	431081	Base	316447	Plug				
Twist Lock		471748	Gasket	510447	i tug				

				Line Driver	Specifications		Isolator Specifications			
		Code	Н	7	F	G	XRB3			
	Description	Symbol	ATEX / IECEx Zone 1 & 21(ia)	ATEX / IECEx Zone 2 & 22	Class I Div. 1 & Zone 0	Class I Div. 2 Listed	ATEX/IECEx Zone 1&21(ia) + Class I Div 1&Zone 0	Units		
	Line Driver		7272	7272	7272	7272	IXDF604			
Input \	/oltage (Nominal)	V _{IN} / V _S	5-7	5-24	5-7	5-24	12-24	V _{DC}		
Input V	/oltage (Max Safe)	UM	N/A	N/A	N/A	N/A	30	V		
Input	Current (no load)	l _{in} / ls	80	80	80	80	150	mA		
Input	Current (Typical)	l _{in} / ls	100	200	100	200	450	mA		
Input	t Current (Max.)	I _{IN} / Is	140	300	140	300	900	mA		
Output	Voltage (nominal)	V _H	N/A	N/A	N/A	N/A	6.8	V _{DC}		
Output Vo	ltage Min.(@140mA)	V _H	N/A	N/A	N/A	N/A	5	V _{DC}		
Output Voltabe Max(No Load)		V _H	N/A	N/A	N/A	N/A	7.14	V _{DC}		
Output Current (@6.8V)		I _H	N/A	N/A	N/A	N/A	115	mA		
Output Current (@5V)		I _H	N/A	N/A	N/A	N/A	140	mA		
Output C	Output Current (short circuit)		N/A	N/A	N/A	N/A	420	mA		
Voltage O	Voltage Output High (Nominal)		5	V _{IN} -1	5	V _{IN} -1	Vs-1	V _{DC}		
Voltage O	utput Low (Nominal)	Vol	.5	.5	.5	.5	.4	V _{DC}		
Signal Cu	urrent (Continuous)	I _{OH} / I _{OL}	100	100	100	100	2580	mA		
Signa	ll Current (Peak)	I _{OH} / I _{OL}	1500	1500	1500	1500	3000	mA		
Outp	ut Resistance Ω	R _{OH} / R _{OL}	15	15	15	15	7	Ω		
(Cable Drive		500	5-15Vin=500 24Vin = 250	500	5-15Vin=500 24Vin = 250	1000	ft.		
	Reverse Voltage		Yes	Yes	Yes	Yes	Yes			
Protection	Short Circuit		Best	Good	Best	Good	Best			
	Transient		Good	Good	Good	Good	Best			
	+Vout		no	Yes	no	Yes	no			
	Alarm		no	Yes	no	Yes	no			
A 1	LED		Yes	Yes	Yes	Yes	Yes			
Alarm	+Vout		Reverence Signal for	r Alarm Circuit, Outp	ut Voltage = Input Vol	tage	•	1		
	Alarm		Open Collector, normally off, goes low on alarm, sink 100mA max, See Connector Pinouts for Availab							
	LED		Green = Power On,	Red = Alarm				1		
	Green - rower on, neu - Alarm									

See the following Installation Drawings for Wiring Information

D53008: ATEX / IECEx Zone 1 & 21

D52353: ATEX / IECEx Zone 2 & 22

D52354: Division 1

D52355: Division 2

NOTE: Remote alarm is not functional for Division 1, Zone 0 or Zone 1

PINOUTS AND PHASING

Phasing is defined as the direction of rotation for which phase A leads B as viewed from the back of the Encoder

viewed from the back of the Encoder	Option Code	Phasing	Signal	0V Gnd	A+	B+	Z+	* Alm+	+Vin		 B-		* Alm
10 Pin MS AvtronPinout	A,B	CW	Pin #	Α	D	Е	C	F	В	G	Н	I	J
10 Pin, Industrial, Avtron Pinout	Р	CW	Pin #	1	2	3	4	5	6	7	8	9	10
10 Pin, Industrial, Northstar Pinout	G	CW	Pin #	1	2	3	4	NC	6	7	8	9	NC
10 Pin MS Mini Twist Lock	R	CW	Pin #	F	Α	В	C	NC	D	Н	J	К	NC
Conduit Box W/10 Pin Terminal Block	4,5,6,7	CW	Pin #	1	2	3	4	5	6	7	8	9	10
10 Wire Cable	W	CW	Color	BLK	GRN	BLU	ORG	BRN	RED	YEL	GRA	WHT	VIO

Phasing is defined as the direction of rotation for which phase A leads B as

rotation for which phase A leads B as	Option	Phasing	Signal	00							
viewed from the back of the Encoder	Ċode	Thasing	Jighat	Gnd	A+	B+	Z+	+Vin		B-	Z-
7 Pin MS, Avtron / BEI Pinout (A,AB,B\)	K	CW	Pin #	F	Α	В	NC	D	С	Е	NC
7 Pin MS, Avtron / BEI Pinout (A,A\)	F	CW	Pin #	F	Α	NC	NC	D	С	NC	NC
7 Pin MS, Avtron / BEI Pinout (A,B,Z)	J	CW	Pin #	F	Α	В	С	D	NC	NC	NC
7 Pin MS, Avtron / BEI Pinout (A,B)	E	CW	Pin #	F	Α	В	NC	D	NC	NC	NC
7 Pin MS, Dynapar Pinout (A,AB,B\)	V	CCW	Pin #	F	Α	В	NC	D	С	Е	NC
7 Pin MS, Dynapar HS35 Pinout (A,A\)	Т	CCW	Pin #	F	Α	NC	NC	D	С	NC	NC
7 Pin MS, Dynapar HS35 Pinout (A,B,Z)	U	CCW	Pin #	F	Α	В	C	D	NC	NC	NC
7 Pin MS, Dynapar HS35 Pinout (A,B)	S	CCW	Pin #	F	Α	В	NC	D	NC	NC	NC

* Remote alarm function not available with line driver options "H", "7" or "F" (Zone 0, Zone 1 or Class I Div I)

THIN-LINE II™

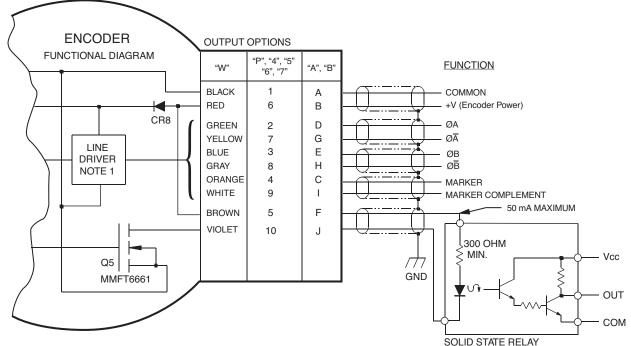
Application Examples

Applies to all XR685 Zone 2 & Division 2models with wiring optons "W", "P", "4", "5", "6", "7", "A" and "B". Remote alarm not available for Zone 0, Zone 1 or Division 1.

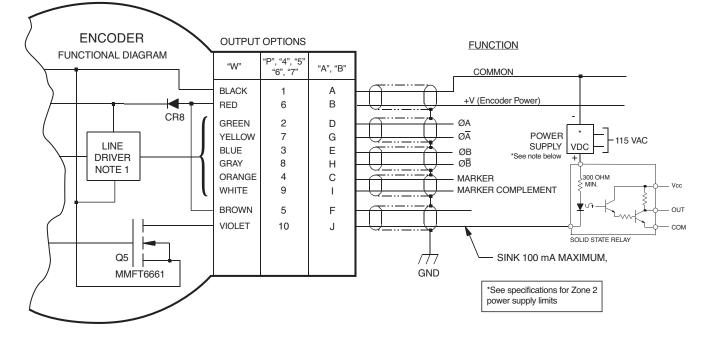
ALARM OUTPUT CONNECTION

Avtron encoders provide an alarm signal if maintenance is required under specific circumstances. An alarm LED indicator is also available. Green indicates power on, red indicates alarm on. Following are application examples provided to help install the alarm output.

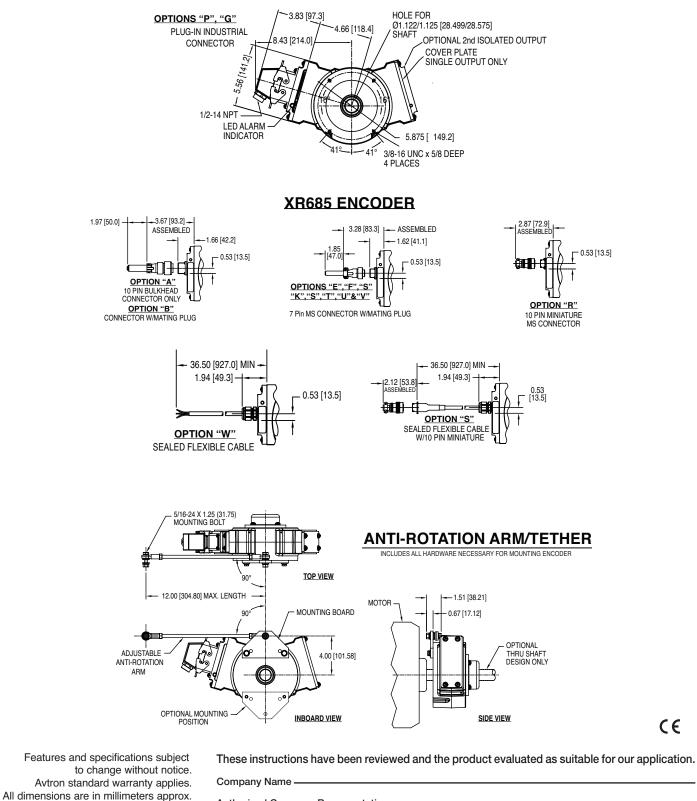
Example 1. Alarm output using +V(OUT). +V(OUT) is equal to +V, the encoder power supply.



Example 2. Alarm Output Using Separate * VDC Power Supply and Relay.



OUTLINE DRAWING



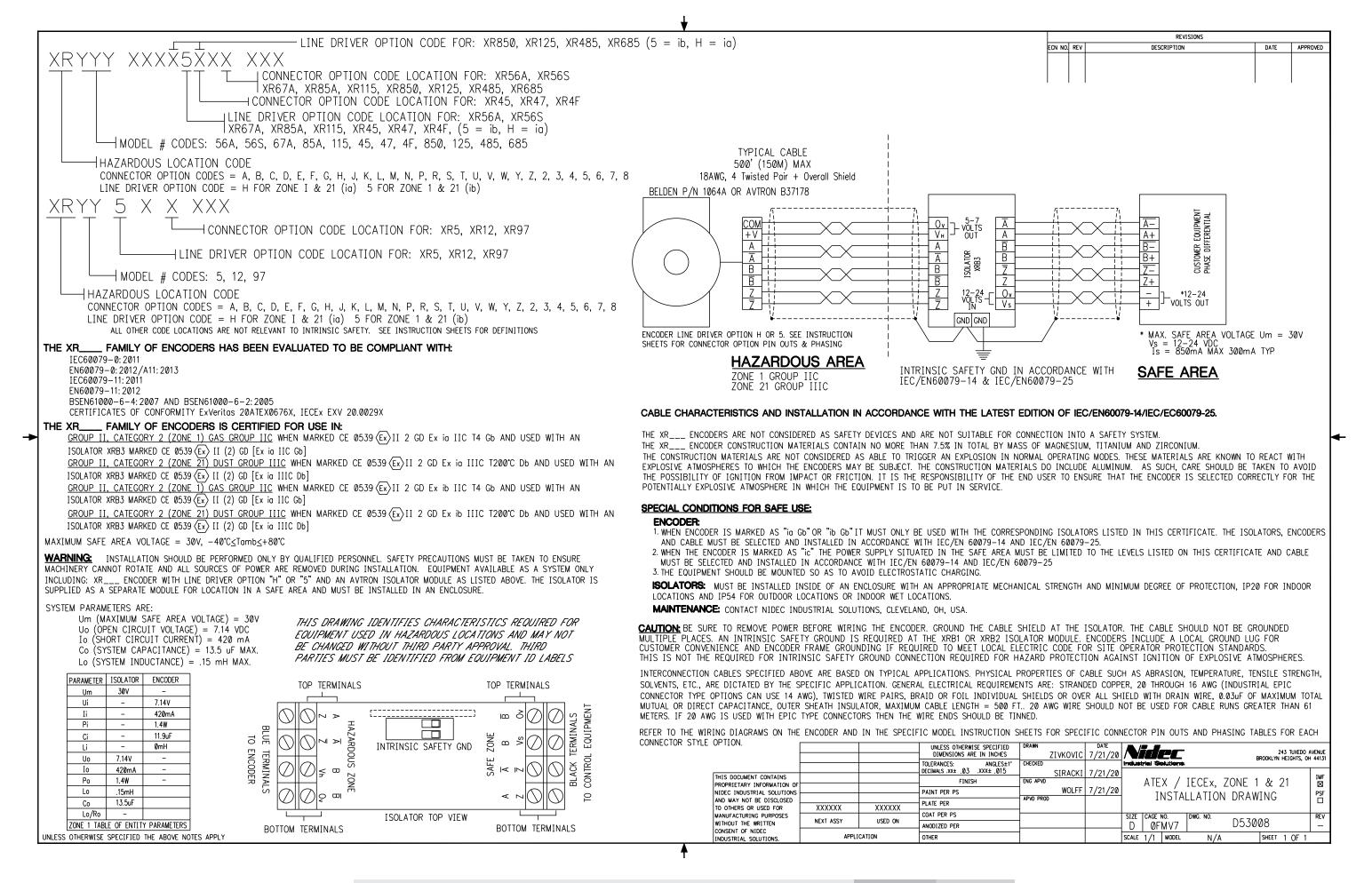
Authorized Company Representative

Title

Nidec Industrial Solutions | 243 Tuxedo Avenue | Cleveland, Ohio 44131 | encoderhelpdesk@nidec-industrial.com +1 216-642-1230 | www.avtronencoders.com

XR685 SMARTSafe[™]

Date



A **Nider** BRAND

XR685 SMARTSafe[™]

Rev: 10-06-2020 10

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₩ KEA	DEMAL DES2223) (] alize cvo			ANODIZED P	no absn	Y22A TX3N	MANUFACTURING PURPOSES WITHOUT THE WRITTEN	The connectors then the wire ends should be
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□ JSd		2/54/12		Sa	PAINT PER			ИОПАМОТИА ИОЯТИА ЭЗДИИ	115, etc., rre dictated by the specific rpplication. 2015 Can USE 14 awg), twisted wire prirs, braid or
NI.	LEX / IECEX ZONE 5' 55		ENG VENDOCK					PROPRIETARY INFORMATING OF	CORPANCE WITH THE NATIONAL ELECTRICAL CODE AND
6700	on Automation		CHECKED						ELECTRIC CODE FOR SITE OPERATOR PROTECTION STANDARD
0405	8901 E.PLEASANT VALLEY R		NICKOLI	IONS ARE IN INCHES					OULD NOT BE GROUNDED MULTIPLE PLACES. ENCODERS INCL
		•		•					ENDENCE' OHIO 44131
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	CCORDANCE WITH THE LATEST				CABLE CI				IE ENCODER IS SELECTED CORRECTLY FOR THE POTENTIN
	JNIZAHY QNA ZTUO NIY NOITYO AO	IS FOR CONNECT	STRUCTION SHEE ZONE 22 GROUP IIIC	SNI 33S		81/2-02 <be2102< td=""><td>ICAL EXAMPLES</td><td></td><td>SAFETY SYSTEM. AND ZIRCONIUM. DES. THESE MATERIALS ARE KNOWN TO REACT WITH.</td></be2102<>	ICAL EXAMPLES		SAFETY SYSTEM. AND ZIRCONIUM. DES. THESE MATERIALS ARE KNOWN TO REACT WITH.
	SAFE AREA	 	IAA SUOGAAZA	Η	<u>"</u>	OBTION <u>"</u> ODEL XR	LINE DRIVER ENCODER MO		aken to ensure machinery cannot rotate and all.
		XX 	40ED 1 PHASE WIF 500' (150M) MA TYPICAL CABLI TYPICAL CABLI					OHIHI 7. ION XVIV ONV	PRATES MUST BE IDENTIFIED FROM EQUIPMEN BE CHANGED WITHOUT THIRD PARACTERISTICS R THIS DRAWING IDENTIFIES CHARACTERISTICS R THIS DRAWING IDENTIFIES CHARACTERISTICS R THIS DRATIES MUST BE IDENTIFIED FROM EQUIPMEN
			יוטבט ז מחזכב זיוונ						× 14 Gc AND FOLLOWNG CHART.

THE XR --- FAMILY OF ENCODERS IS CERTIFIED FOR USE IN: CERTIFICATES OF CONFORMITY TRAC12ATEX0003X, IECEX TRC12.0009X BSEN01000-6-4:2007 AND BSEN01000-6-2:2005

IEC60079-11:2011, EN60079-11:2012

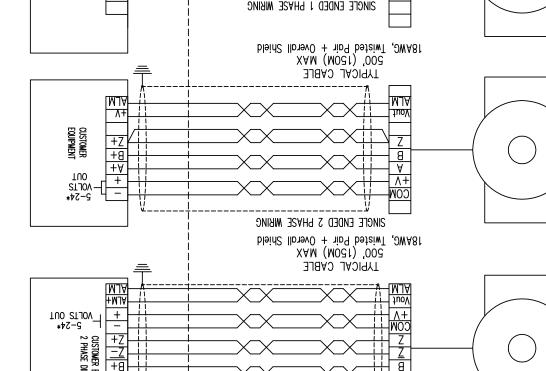
IEC60079-0:2011, EN60079-0:2012/A11:2013 THE XR --- FAMILY OF ENCODERS HAS BEEN EVALUATED TO BE COMPLIANT WITH: SEE INSTRUCTION SHEETS FOR DEFINITIONS ALL OTHER CODE LOCATIONS ARE NOT RELEVANT TO INTRINSIC SAFETY LINE DRIVER OPTION CODE = 7 FOR ZONE 2 & 22 CONNECTOR OPTION CODES = A, B, C, D, E, F, G, H, J, K, L, M, N, P, R, S, T, U, V, W, Y, Z, Z, Z, 4, 5, 6, 7, 8 HAZARDOUS LOCATION CODE

> LINE DRIVER OPTION CODE LOCATION FOR: XR5, XR12, XR97 Х Х С ТҮЯХ XXX TINE DKINEK OBLION CODE = 1 LOK ZONE 5 & 55 HAZARDOUS LOCATION CODE

CONNECTOR OPTION CODE LOCATION FOR: XR3, XR12, XR97 CONNECTOR OPTION CODES = A, B, C, D, E, F, G, H, J, K, L, M, N, P, R, S, T, U, V, W, Y, Z, 2, 3, 4, 5, 6, 7, 8 4 WODEF # CODE2: 264' 262' 674' 824' 115' 45' 47' 4F, 850, 125, 485, 685

ΥΑ57Α, ΧΡ35Α, ΧΡ115, ΧΡ45, ΧΡ45, ΧΡ45 LUNE DRIVER OPTION CODE LOCATION FOR: XR56A, XR56S CONNECTOR OPTION CODE LOCATION FOR: XR45, XR47, XR4F TXR67A, XR85A, XR115, XR850, XR125, XR485, XR568 CONNECTOR OPTION CODE LOCATION FOR: XR56A, XR56S

- FINE DKIVER OPTION CODE FOR XR850, XR125, XR485, XR685



+8 +∀⊦ A DIFFERENTIAL 2 PHASE WIRING EA0878 A ADD SPECIAL CONDITIONS FOR SAFE USE PATTON 6/24/15 SHADDUCK APPROVED DATE DESCRIPTION CN NO BEA REVISIONS

NULESS OTHERWISE SPECIFIED THE ABOVE NOTES APPLY

=500 FT.. 20 AWG WIRE SHOULD NOT BE USED FOR CABLE RUNS GREATER THAN 61 METERS. IF 20 AWG IS USED WITH EPIC TYPE CONNI FOIL INDIVIDUAL SHIELDS OR OVER ALL SHIELD WITH DRAIN WRE, 0.050F OF MAXIMUM TOTAL MUTUAL OR DIRECT CAPRICITANCE, OUTER SI GENERAL ELECTRICAL REQUIREMENTS ARE: STRANDED COPPER, 20 THROUCH 16 AWC (INDUSTRIAL EPIC CONNECTOR TYPE OPTIONS CAN U CANADIAN ELECTRICAL CODE. PHYSICAL PROPERTIES OF CABLE SUCH AS ABRASION, TEMPERATURE, TENSILE STRENGTH, SOLVENTS, ETC., INTERCONNECTION CABLES SPECIFIED ARE BASED ON TYPICAL APPLICATIONS. CABLE MUST BE SELECTED AND INSTALLED IN ACCORDANCE CROUND LUC FOR CUSTOMER CONVENIENCE AND ENCODER FRAME GROUNDING WITH 14 AWG WIRE IF REQUIRED TO MEET LOCAL ELECTRIC CAUTION: BE SURE TO REMOVE POWER BEFORE WRING THE ENCODER. GROUND THE CABLE SHIELD. THE CABLE SHIELD SHOULD NOT

MAINTENANCE: CONTACT NIDEC AVTRON AUTOMATION CORPORATION, 8901 EAST PLEASANT VALLEY ROAD, INDEPENDENCE, 2. THE EQUIPMENT SHOULD BE MOUNTED SO AS TO AVOID ELECTROSTATIC CHARGING. BE SELECTED AND INSTALLED IN ACCORDANCE WITH IEC/EN 60079-14 AND IEC/EN 60079-25 1. When the encoder is marked as "ig" the power supply situated in the safe area must be limited to the level ENCODER:

SPECIAL CONDITIONS FOR SAFE USE:

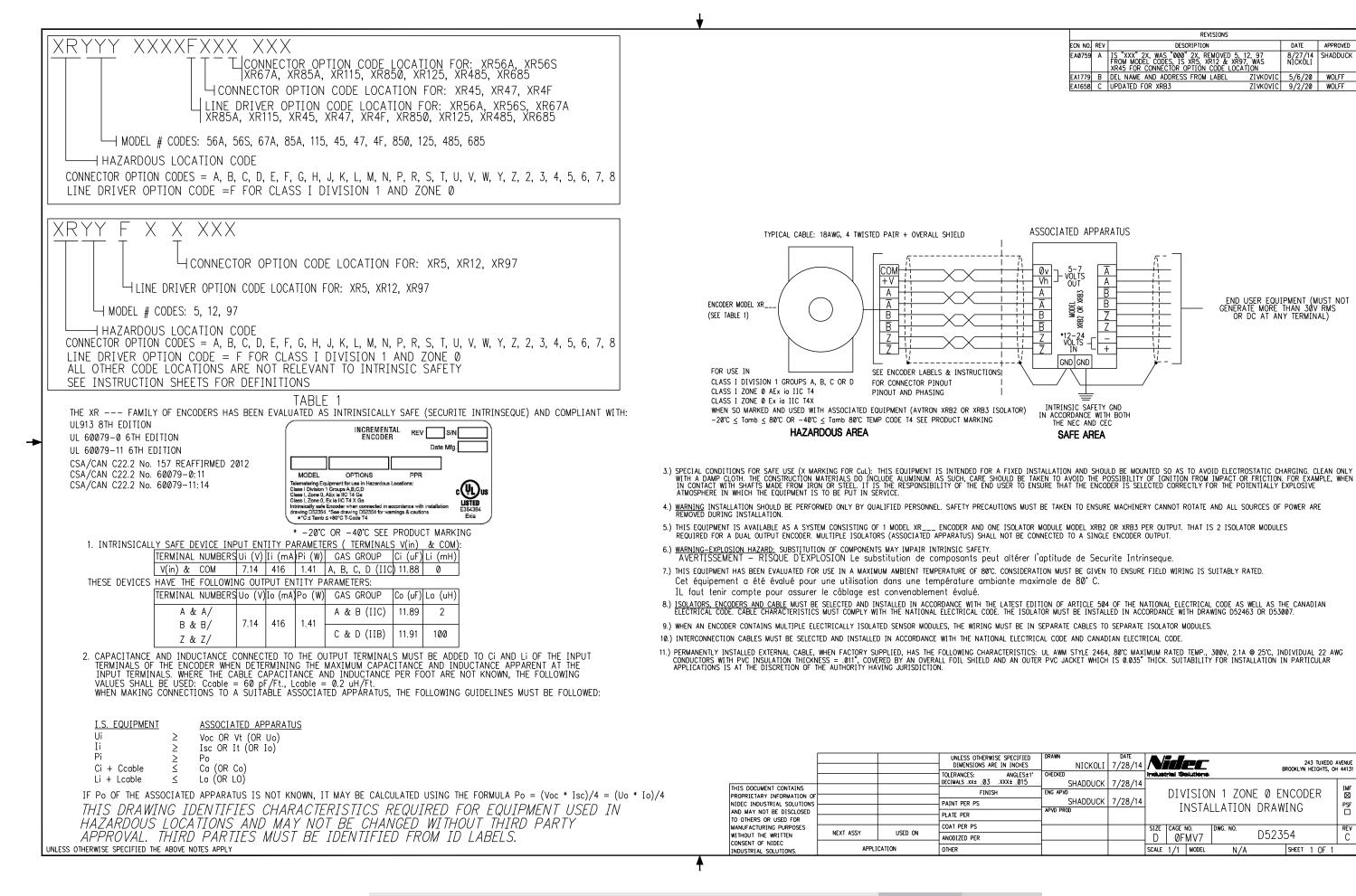
EXPLOSIVE ATMOSPHERE IN WHICH THE EQUIPMENT IS TO BE PUT IN SERVICE. POSSIBILITY OF IGNITION FROM IMPACT OR FRICTION. IT IS THE RESPONSIBILITY OF THE END USER TO ENSURE THAT THE ENCODE EXPLOSIVE ATMOSPHERES TO WHICH THE ENCODERS MAY BE SUBJECT. THE CONSTRUCTION MATERIALS DO INCLUDE ALUMINUM. SOURCES OF POWER ARE REMOVED DURING INSTALLATION. WARNING: INSTRLATION SHOULD BE PERFORMED ONLY BY QUALIFIED PERSONNEL. SAFETY PRECAUTIONS MUST BE TAKEN TO

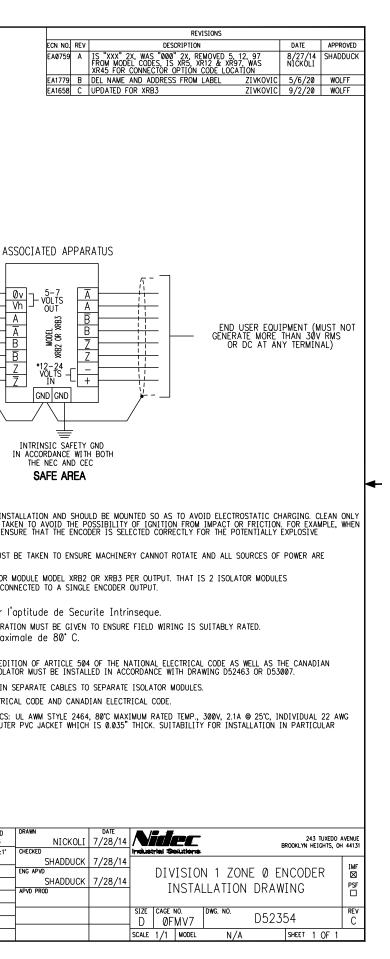
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	81	IIC	
C!	!	n	!!
TABLE 1: ZONE 2 POWER SUPPLY LIMITS			

J°08+≥dmpT≥J°04-

GROUP II, CATEGORY 3 (ZONE 22) DUST GROUP IIIC WHEN MARKED CE <Ex∕II 3 GD Ex ic IIIC T200° USED WITH A SELV OR EQUIVILENT POWER SUPPLY THAT LIMITS VOLTAGE AND CURRENT PER THE FOLLOWING GROUP II, CATEGORY 3 (ZONE 2) GAS GROUP IIC WHEN MARKED CE (Ex)II 3 GD Ex ic IIC* T4 Gc AND

→ WODEF # CODE2: 2' 15' 3





13 Rev: 10-06-2020 ^{M1}91s2TAAM2 280AX

UNARB JULINA

